

SIMULATION OF A TANK BATTLE ON COMPUTERS

A Thesis Submitted
in Partial Fulfilment of the Requirements
for the Degree of
MASTER OF TECHNOLOGY

By
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to the
DEPARTMENT OF ELECTRICAL ENGINEERING
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SEPTEMBER, 1981

CERTIFICATE

This is to certify that the thesis entitled
'SIMULATION OF A TANK BATTLE EXERCISE ON COMPUTERS'
by Capt. Vinay Sagar is a record of work carried out
under my guidance and has not been submitted elsewhere
for a degree.

Sept. 1981

A handwritten signature in black ink, appearing to be 'V. Rajaraman', with a long horizontal stroke extending to the right.

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ACKNOWLEDGEMENT

I would like to thank Dr. V. Rajaraman, my thesis supervisor for all the help and guidance he has given me. It has given me great pleasure to work under him and get his valuable advice.

I would also like to thank Mr. J.S. Rawat for typing out this thesis neatly.

Capt. Vinay Sagar

ABSTRACT

An interactive simulator for tactical exercise with battle tanks has been described here. The effort has been to make this simulator a logical extension of a sand model exercise, so that a more realistic exercise which is closer to real exercises in field may be achieved.

The topographical details of a map area required to be used, is stored in the memory. The user is permitted to give commands to MOVE and FIRE. The move and fire is simulated taking into consideration the topographical details, characteristics of armour and the firing capability of tanks. The REPORT facility in the simulator helps the user in gaining information regarding tank status and other details used for taking decisions.

It is considered that simulator when fully developed will form a useful aid in exercising a squadron as a team, in which the squadron commander along with his troop commanders can participate.

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CHAPTER 1

INTRODUCTION

In Army, tactical exercises form an important part in troop training. These exercises involve the process of making decisions under visualised situation to resemble true combat situation. Troop commanders are exercised under constraints of carefully planned rules, as they would under combat conditions.

Field Exercises are very costly and have other effects like cost in fuel consumption, wear and tear of equipment and wastage. Wear and tear of tanks is an important factor which reduces the tank life considerably. As such frequent field exercises involving tanks are not possible. Moreover the area available for such exercises is restricted. Built up areas cannot be used for exercise and firing because of the damage it would cause. Also exercise cannot be done in critical areas like borders etc. Therefore at present the use of 'Sand Model' to exercise the personnel in tactics is the most commonly used method. Any form of exercise being at best, a poor substitute for experience, the emphasis is therefore more on realism and greater detail. The objective of this thesis is to develop

a computer based interactive simulation in an effort to replace the sand model exercise with increased reality and more details.

1.1 The Importance of a Simulator;

The simulator comes in between the sand model and field exercise and can have certain advantages over it. Some of the essential features of the simulator are described in the succeeding paragraphs.

The preparation of a sand model is time consuming and even then all the details cannot be represented on it. In contrast in the computer simulation the representation of the topography exists in the memory of the computer which can be more exhaustive than a sand model.

The hypothetical vehicle i.e. tank in this case is 'moved' and can 'fire' taking into account the factors that govern movement such as terrain, gradient, mobility and for fire accuracy of gun, rate of fire and penetration etc.

Visibility and sighting of the tanks is decided by the computer depending on the topographical information available with the computer. Factors that decide visibility like cover, concealment and line of sight is accounted for.

Communication, queries and replies between the simulated tanks by the commanders can be done through the computer.

Freedom of action is available to the participating personnel and pre-determined action is curtailed so that the exercise is allowed to take its course of action.

1.2 Review of Similar work done earlier:

In recent past a lot of thought is going in this direction of simulation on computer mainly because of the economics of time, cost and effort saving that it offers.

Known similar work has been done on 'war gaming' [1], in which a game is described where in two opposing forces are made to 'move' from one point to another according to a battle plan. During this course of movement analysis is done so that if enemy is sighted then it fires a fixed number of rounds/shells on it. In the end the success or failure is evaluated in terms of quantum of forces that have reached their destination.

Another work that has been done has been on 'Computers and Tactical war gaming' [2]. This is a theoretical description on how simulation can be done for a tank battle at squadron level. This work describes how computer can be

used to exercise the commanders i.e. squadron and troop commanders in taking decision in near real life situation. This is more of an interactive process as would be seen in an exercise. The idea for this thesis is based on this work and simulation programmes have been developed in PASCAL for its implementation on Dec 1090.

1.3 Goal of this Thesis:

The goal of this thesis is 'To write the necessary programmes to realise the command and communication repertoire in a higher level computer language for simulation of tank battle'.

To achieve the above goal the following essential features are considered necessary:

- a) A detailed description of battle area topography to be stored in the memory. Roads, rivers, obstacles, minefields, untankable country etc. are depicted so that the exercise can be simulated on any desired type of terrain or area for which map is available.
- b) Detailed description of every participating element, including its characteristics of tank and armament.

- c) The tanks in the memory are 'moved' taking into account the factors that govern movement like terrain, obstacles etc. Gains and losses are decided upon, appropriate to firepower, accuracies of the gun, rate of fire, penetration etc.
- d) Factors deciding visibility such as cover, concealment and direct visibility are catered for.
- e) Tactical decisions are made by the users. They type in command and queries and receive replies in a normal form.
- f) A set of factors additional to that mentioned above like artillery, anti-tank weapons, air support could be included to give more realistic and complex view.

To complete the simulation of a squadron level tank exercise, in addition to this part, development of the requisite interface to couple the necessary consoles and other aids used is required. This could be done as a further development to this thesis. When this is done, then this could be used to exercise the squadrons i.e. the squadron commander along with troop commanders for a tank battle.

1.4 Chapter Summaries:

In the next chapter we review the computer aids available for tactical exercises and war gaming. In this methods available for war gaming, the importance of Tactics/Strategy and any known work in this field will be discussed.

The complete 'over view' of the system will be given in Chapter III. This will give the block diagram of the system developed and what is expected of each block. Interconnections between these blocks and how to use the developed system will be described.

Chapter IV will give some specific algorithms that have been used. Approximations and assumptions made in developing this system will be discussed with possible improvements and the type of computer required for implementation of such a programme.

The graphic aid used by the simulator and a 'test exercise' will be described in the next chapter. The last chapter gives the conclusions and suggestions for further work.

CHAPTER II

WAR GAMING ON COMPUTER

War gaming has become a recognised technique in relatively recent times, but its essence has been a part of the pre-planning that military commanders have done through the ages. The military services would define a war game as a simulation, by whatever means, of a military operation involving two or more opposing forces, conducted, using rules, data and procedures designed to depict an actual or assumed real life situation. The simulated warfare provides a means of gaining experience, identifying errors or short-comings and improving skills without paying the penalties of the real war. Any thing in this world which is as costly as a war impels a search for its substitute.

2.1 War Gaming:

In military most of the important problems are amenable to analytical study. At present war gaming is mainly used for the following purposes:

- a) To train military personnel
- b) To test plans of commanders
- c) For research, to explore new concepts.

Generally the above three purposes are clearly specified and well defined for each game. In some cases it could be used for multiple purpose as well, like for training as well as testing of plans. Games for research are usually conducted to study matters associated with new concepts. They also include the evaluation of plan and/or the formulation of doctrine in the application of new concepts. These three major purposes of war gaming are very much inter-related and also represent the stages of progressive development of war gaming.

War games normally attempt to develop and use models to represent the actions in a game. The model is important in a simulation. In a war game some factors not explicitly quantified in the model can be added by the controller, specified in the rules as input data, or covered as rules in the game assumptions. So effective models of battle can be built for some of the important factors involved in combat, but not all. Too little is known about the geometry of battle. Even information on the rate of casualty production and the resulting effects is inadequate to build precise mathematical equations. Formulae and model from historical records have some validity but have predictive value in a general way only. Although such models are

useful, they do not provide all the interactions and measures of effect needed for many analytical purposes. The object of the game will then be served by comparative rather than absolute casualty figures. Such a model is only as good as the capability of the model builder to build military sophistication and battle logic-expertise into the model.

2.2 Tactics/Strategy:

Some basic characteristics of war games normally found in all of them are:

- a) Every war games simulates a military operation (irrespective of phase or manner of gaming).
- b) Each game involves two or more opposing forces.
- c) Each war game is conducted in accordance with data, rules and procedures acceptable to the military profession.
- d) Every war game represents an actual or assumed real life situation.

An activity cannot be termed a war game unless military forces are involved in movements or operations accompanied by the clash of arms or the threat of such a clash. War

games are played only under conditions of simulated war-fare i.e. shooting, attack, or invasion by one force upon the territory of another. War game rarely consider non-shooting situations unless the situation is an interlude during which forces get into position or range to fight.

Therefore a war game is built upon a situation such as exists or realistically could exist in some locale under certain assumed conditions. The situation is described in detail sufficient for the commander to visualise the conditions under which he must conduct military operation.

Taking the above conditions in view the following ingredients are necessary for war gaming:

- a) Knowledgeable personnel
- b) Special facilities and equipments
- c) Standard data, rules and procedures
- d) A description of the situation to be represented in the game.

2.3 Other work in this Area:

The 'Tin Soldier' which became operable in 1952, is believed to be the first war game designed as a mathematical model for use on a computer in analytical research studies.

This war game is simple and is described as follows. A map is given for the area of interest and on it are

marked the various status of troops of pre-battle conditions for both the opposing forces. It essentially involves two forces, own and enemy forces. Then one man each is permitted to 'head' these forces. Their aim being to guide their forces in an imaginary battle. The battle is then organised to progress under the rules agreed as follows.

- a) Each man is permitted to move his tanks/forces that would correspond to 't' seconds elapsed time on real terrain, consistent with the mobility capabilities of the tank.
- b) After each man moves his tanks/troops according to his military good sense, tanks within range are assumed to bring fire on the opposition. The winner of tank duel is decided by flipping a loaded coin that is supposed to express the odd on the battle outcome in actual fighting between these tanks.
- c) The battle is over as soon as all tanks on either side have been knocked out or have made successful withdrawal from the battle field.

The next step to this was the computerised Monte Carlo version called 'The maximum Complexity Computer Battle', capable of dealing with more of the variables of actual battle. The technique employed is called 'pseudo-random

number generator'. Every time this random number generator is referred, a large sequence of numbers (R) are computed, so that the sequence is practically random as far as the observer is concerned. If the probability of an event 'E' taking place is 'p', p being between '0' to '1', the following procedure simulates the occurrence of E:

if $R \leq p$, E occurs otherwise not.

Every time procedure is called, R is re-computed and compared with 'p'. Over a large number of calls, 'E' will occur the specified percentage of times. In addition in deciding the occurrence or non-occurrence of probabilistic events, the Monte-Carlo technique also provides for the determination of variables used in simulation in a probabilistic manner.

While the technique described here is satisfactory as a first approximation, it is necessary to add several refinements in practice. The uniform distribution of random variables is not common in practice.

Other methods used for formulation are the 'Next-Event formulation' and 'Fixed time step formulation'. The basic difference between the two is of time of computation. In the first i.e. next event formulation the time period used

is the time that will elapse between two subsequent events. Hence this time period varies as the simulation progresses. Whereas in 'fixed time', the time period of computation is kept constant to a pre-determined value.

With the 'next event' model, the processing of event occurrences proceed occurrence by occurrence as follows. The simulation time is advanced to the time of the earliest future occurrence. That occurrence is processed, then the simulation time is advanced to the time of the (new) earliest occurrence and that occurrence is processed and so on. However, with the fixed time-step model, the processing of event occurrences does not proceed occurrence by occurrence in this way. Rather it proceeds by group or batches of event occurrences. All event occurrences during the time step are processed together.

With the 'next-event' model the need to choose an arbitrary and artificial increment does not exist, and the pit-fall of picking a suitable increment is avoided entirely. In this respect, the next event formulation is preferable to the fixed time step formulations. Further more in a next-event model two event occurrences are not processed as simultaneous events unless they bear identical occurrence times. In a time-step model, on the other hand, batches of

non-simultaneous occurrences are grouped together and made to appear simultaneous. Thus, simultaneity is created where it need not exist. In order to process simultaneous occurrences, any simulation model must make use of some rule for determining the sequence in which to process the occurrences. Fixed time-step simulation then, often takes a group of non-simultaneous event occurrences, forces them to be simultaneous and process them in some sequence.

One situation, however, may require a user to use a time-step model instead of a next-event model. This is the situation where a next-event model takes a prohibitively long time to run on a computer and where the artificialities and inaccuracies of the time step model do not destroy the usefulness of the results. If the time increment, in fixed time step is sufficiently large, it is possible that the fixed time-step simulation may progress significantly faster than the corresponding next event simulation.

In this thesis the model of fixed time-step which can be modified to different values during the simulation is used. The capacity to modify the time step gives the option to the user to make a trade off between accuracy and speed. Thus the user is able to decide during the

simulation process, depending on the status or the situation that exists at that moment. If the user feels that the time step is to be reduced or increased, he can do so at that time.

2.4 Inter-active Simulation:

On computer there are two main types of simulation, one is complete computer simulation and another is man-computer simulation or interactive simulation. In the all computer simulation the input data and the rules are pre-described and given to the computer. The computer then simulates that action and reaches the result or conclusion. In this a number of runs would yield similar results because of the uniform strategy/decision of processing. Whereas inter-active simulation is different and would give different results with each user.

In this, instead of producing a complete history automatically in one continuous operation such a routine processes events until an event is reached where a human decision is necessary or additional input is required. Then the routine causes the computer to wait for appropriate action to be taken before it starts another 'computer phase' of simulation. This is near to real time exercises

conducted by the armed forces and therefore better suited to simulate battle exercises. The simulator described here uses this interactive process of simulation.

Each interval during which the computer waits for input or for decisions is called a 'wait phase' of simulation. During this phase one or more team is in action. A team may be deciding on the movements of units, determining firing and communication policies to be followed, assessing information they have received about their own and enemy's units, and so on. The end of this phase occurs when the information requested by the computer is made available to restart the computer simulation routine.

The most obvious difference between a computer routine for man-computer gaming and a complete computer simulation routine is that the former must be able to 'converse' with the human players. For instance, the routine must be able to inform the players whenever any unit require repair, fuel etc. The routine must also inform the human players of enemy detections, firing of weapons, and damage sustained or inflicted. Each message is delivered through a computer output unit to the appropriate team or player.

An interactive game has some undesirable features which are associated with the alternating of the game. For example,

a 'wait phase' once begun must continue until it produces the decisions or other information which allow another computer phase to be started. Since this corresponds to stopping battles while decisions are being made, it is a poor representation of a real situation. Any attempt to place time limits on the 'wait phase' of the game requires rules which bear little relation to the real situation that one is trying to portray. Also the computer phase of the game must stop whenever any team must furnish information required by the computer simulation routine. This may cause delays unexplainable to one team or the other. For such reasons as these, use of 'synchronized' man-computer game is used where both 'wait' and 'computer' phases run continuously and concurrently with the use of 'clock'.

CHAPTER III

OVER VIEW

Tank battle simulation consists of essentially the storage of data concerning each tank and its subsequent updating depending on the commands given by the user. The data on each tank is stored in a record TNKDAT and has the following fields.

TYPNO: (1..5); Gives the type of Tank. Caters for a maximum of 5 types.

MAPCORD: X,Y; (INTEGER); Gives location of the tank in X and Y co-ordinates.

ORNTASN:(0..360); Gives the direction in which the tank is facing.

AMNCAP :TYP1, TYP2, TYP3: (INTEGER); Gives the amount of ammunition that is available with the tank. Caters for 3 different type of ammunition.

FUELCAP:(INTEGER); Gives the Quantity of fuel that is available with tank.

ALT : (INTEGER); Altitude in metres where the tank is located.

LODIME:(INTEGER); The time taken to load the shells before it is fired once the command to fire has been given.

STATUS:

BOGGED:(BOOLEAN); States whether the tank
is bogged.

MOVING: (BOOLEAN); Whether the tank is moving,
used to calculate rate of fire etc.

CANMOV:(BOOLEAN); Used when command to move
is given.

FIRING:(BOOLEAN); States whether the tank is
firing on target.

CUPOLACLOSED:(BOOLEAN); Used for visibility
calculation.

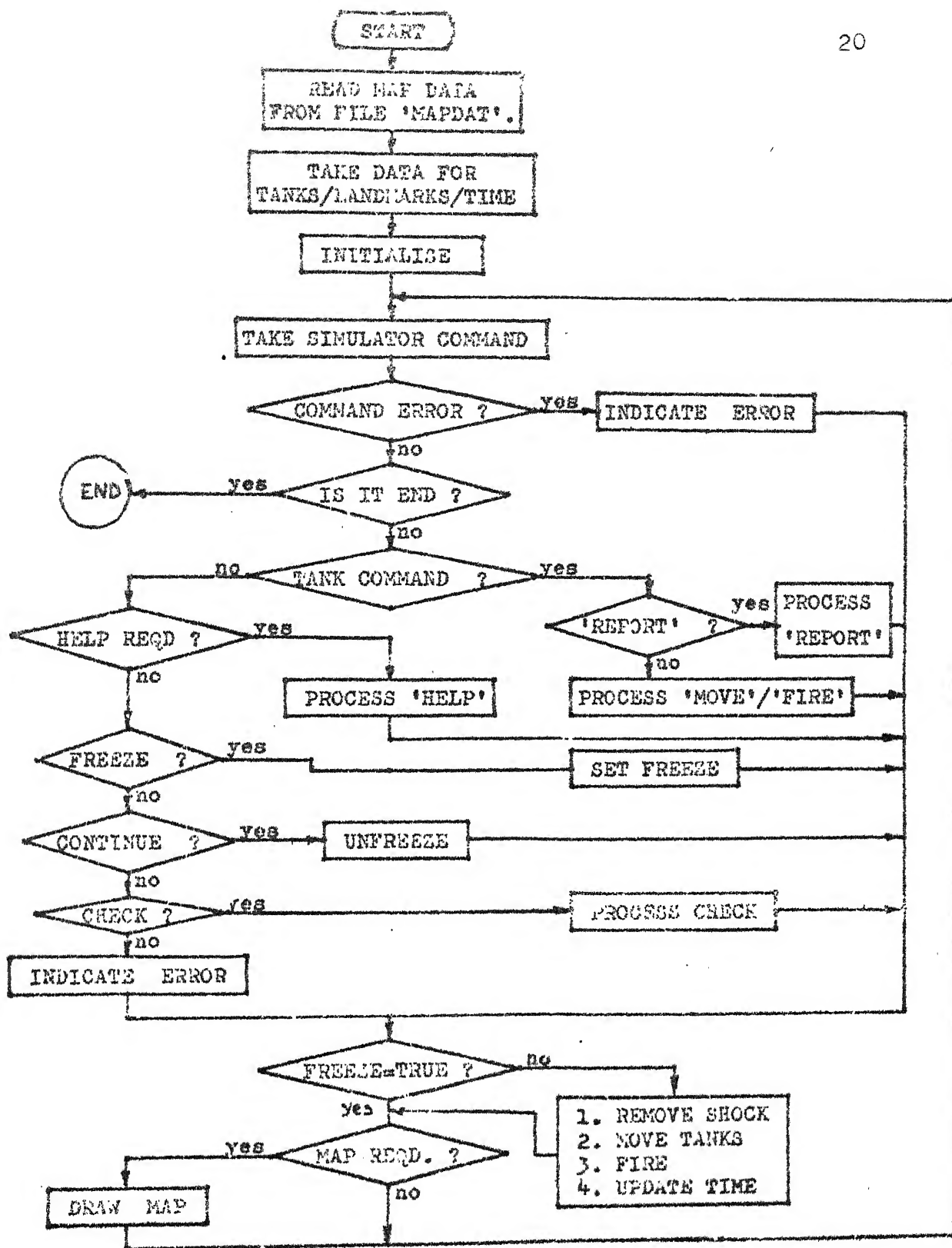
NUETRALISED:(BOOLEAN); Whether tank is incapa-
citated and can take no further part.

SHOCKED:(BOOLEAN); Temporarily out of action,
will not respond in that duration.

Various data from these fields can be 'read' through
REPORT procedures which help the user in taking decision.

These data also form the base for generation of other tables.

The simulation of MOVE and FIRE are done through the
use of temporary tables which are processed to change the
records of the affected tank in TNKDAT.



The flow chart for the simulation process is shown as Fig. 1. This could be divided into the following sub-systems.

- a) Map Generation
- b) Initialization
- c) Command Processing
- d) Report
- e) Information/Help
- f) Update Records
- g) Action
- h) Graphic Display

3.1 Goals for Each Block:

Map Generation:

This part deals with the description of map details. This is a time consuming process and hence is separated from the main programme. The map is drawn with an interactive dialogue. The validity of the input with respect to the restrictions imposed for drawing the map are checked and then a file is created for the use of the main programme. This consists of the following 2 parts.

(a) Checking of Input:

Due to the limitations and economy of computer usage

some restrictions have been imposed for describing the details of a map. They are

- i) Grid points are limited to a maximum of 40x40.
- ii) Each grid point is at a distance of 500 mtr apart.
- iii) Details such as rivers, canals etc. have been approximated as straight lines between turning points.

(b) Creating Data Files:

The above facts are checked as and when the map is being drawn. If it is within these constraints then this data is written into a file 'MAPDAT' which forms an input to the main programme. In addition another file 'MAP' is created to facilitate the drawing of map on Graphic terminal and avoid duplicating of calculation.

Initialise:

This is used for starting the simulation of the exercise. This consists of initialising the following:

(a) Map Details:

Reading the map data from file MAPDAT and storing the map details.

(b) Tank Details:

Initialising/reading the characteristics of the type of tanks used and their location at start.

(c) Graphics:

Initialising the graphic device to be used and resetting its data file MAP for its use.

(d) Land marks:

Taking in interactively the various landmarks that are likely to be used during the exercise and storing them for reference in LMTAB.

(e) Time:

If required, updating the 'Time step' to be used for each iteration. Also takes in the start time of the exercise.

(f) Variables:

Initializing the various pointers arrays and variables used in the programme.

Command Processing:

This is the main block of the system. It takes in one command at a time, analysis it and then appropriately calls the block required. The following facilities are available:

- a) The command is analysed for its syntax error and if error exists, then this is indicated to the user.
- b) Facility to 'freeze' all action and 'un-freeze' it when required.
- c) Updates the time that has elapsed since the start time, if action is not frozen.
- d) Process 'help' for MOVE, FIRE and REPORT.
- e) Change time step if required, during execution of the programme.

Report:

This block is essentially a report back answer to queries addressed to the various tanks. Most of the details are taken from record TNKDAT. The report could be concerning the following.

(a) Location :

This reports the 4 figure grid reference on the map. This could be of

- i) Self
- ii) Another tank.

(b) Status:

This concerns the various activities that a tank could do or is doing. This refers to whether the tank is

- i) Bogged
- ii) Moving
- iii) Can move
- iv) Can shoot
- v) Neutralized

Once a tank is neutralized then it can take no further part in the exercise and will not respond to any command.

(c) Visibility:

Checks if the other tank or location is visible to the addressed tank taking into consideration the following.

- i) Time of day
- ii) Equipment available for visibility at that time of day.
- iii) Cover available to target
- iv) Intermediate obstruction in the line of sight of these 2 points.

(d) Balance:

Balance of 2 commodities can be asked for

- i) Fuel: This includes reserve as well
- ii) Ammunition: This can be asked for a specific type of ammunition i.e.
 - (aa) HE (High Explosive)
 - (ab) AP (Armour Piercing)
 - (ac) SMOKE

By default, if no particular type is specified, then all types will be listed with their balance.

Information/Help:

This contains the information regarding the various modules, facilities that are available and how to use them. It essentially contains information regarding the following:

(a) HELP IN

- i) Commands
- ii) Report
- iii) Move
- iv) Fire

(b) CHECKING

- i) List of land marks defined
- ii) List of Tanks on move
- iii) To change time step
- iv) Set/unset drawing of a map
- v) Display map.

This can be called for by HELP/CHECK and then choose the information in the type required by you. For 'help' it lists out the possible commands in that field with options. This forms the command communication language and is approximated to the actual commands that are normally used, keeping in mind its application on the computer. Commands available are given as Appendix A.

UPDATE RECORDS

When ever any 'Move' or 'Fire' command is given, details regarding the affected tanks is stored in records for further processing in the 'Action' part. This part does the following.

- (a) Checks if the command is correct otherwise the error is indicated to the user.
- (b) If the command is correct then it extracts information to be stored in the respective Move/Fire tables. The details are:
 - i) For Move: This data is stored in a chained record-MOVTAB with following details:
 - (aa) Starting location
 - (ab) Destination
 - (ac) Route - maximum of 10 intermediate points are catered for.

- (ad) Current location
- (ae) Name of tank
- ii) For FIRE: The data for this is stored in record-FIRETAB . It consists of the following details
 - (aa) Name of tank
 - (ab) Target location
 - (ac) Target tank No. if any
 - (ad) No. of shells to be fired.
 - (ae) Rate of fire
 - (af) Hit probability
 - (ag) Type of shells to be fired

These tables form the basis for the other blocks which do the 'Action' part. Once the action is complete then that particular record is deleted from the chain. Therefore only the currently required information is stored in these chains.

Action:

This is essentially simulating the 'move' and 'fire' action in the system. The input to this is taken from the records FIRETAB for 'Fire' and MOVTAB for 'move'. For every cycle of time the following action part is done.

- (a) For MOVE: For each of its record in MOVTAB it does the following:

- i) Checks if the status is not neutralized, if it is not then it will start the move process.
 - ii) It will then take its next objective and calculate the next grid point that it has to move.
 - iii) Before 'moving' to the next grid point, checks for its topography whether there is a river, canal, minefield etc. and takes appropriate action.
 - iv) If it can move to the next grid point then calculates the following
 - (aa) Time taken for this move
 - (ab) Fuel spentand updates both these quantities.
 - v) Thus it will continue till either it reaches its destination, is stopped or the time step is over.
- (b) Fire: When 'fire' is to be done the following is done for each record of its table 'FIRETAB'.

If the status of the tank is not neutralized then each time period, it will fire the shells depending on the following

- i) Rate of fire of the tank depending on whether it is moving or stationary. This is taken from the tank status in TNKDAT.

- ii) Calculate the location of hit taking into consideration the probability of hit and ranging.
- iii) Analysing the hit with respect to the target tank i.e. angle of hit, distance and type of ammunition used. Then accordingly changes the status of the effected tank if needed.
- iv) It will continue this till the required number of shells are fired or time step finishes or is commanded to stop firing.

Graphic Display:

Then lastly the complete activity is displayed on the Graphic terminal. The display consists of the following

- (a) Details of the map which include the following
 - i) Rivers
 - ii) Roads
 - iii) Canals
 - iv) Minefields
 - v) Marshy ground
 - vi) Fields/High grass
- (b) The map displays the area of 20x20 km divided into 40x40 grid points i.e. each grid point is at a distance of 500 mtr apart.

- (c) For referencing on the map, grid marks are available at 2.5 kms distance (5 grid points).
- (d) The 'land marks' defined by the user is also displayed at the location with the assigned name.
- (e) Location of all tanks, as they are located at the time of display of the map.
- (f) Location of hit of the shell at the time of display if there is any.
- (g) Contours are displayed at an interval of 50 mtr. This is done with relative height, with the surrounding ground taken as '0'.

3.2 Interconnections:

The common record for the complete programme is TNKDAT. There are other subsidiary records to this record which are used to update this during the exercise.

The map data generated is primarily used for the 'move' and display purposes. This data is kept in GRIDCHAR. When the move is simulated then details regarding the ground is used for calculation of speed, fuel spent and obstacles enroute.

After calculation of fuel spent and new location, they are updated in the record TNKDAT. If there is any change in status like the tank is bogged, neutralized etc.

the same is changed in the 'status' field of TNKDAT.
Therefore the latest information is stored in the record
TNKDAT.

When 'Fire' has to be done. The shells are fired
from the tank depending on the command given and the same
number as and when fired are reduced from its record of
that particular tank. The location of hit is calculated
and then the effect of shell analysed depending on the type
of shell and location of target damage if any is reflected
through TNKDAT.

'Shocked' is a temporary status wherein the tank
is not able to respond to your command for one cycle of
time. The 'shocked' status removal is directly done through
the main programme.

3.3 How to use the Simulator:

There are 2 programmes in the system which are to be
used in the following sequence.

(a) MAPRIT.PAS

(b) BATTLE.PAS

MAPRIT.PAS

The programme MAPRIT.PAS is used to describe the
topography of the area that is being used. The following

data regarding the details to be described must be available at the time of execution.

(a) RIVERS/CANALS

- i) Direction of flow of water
- ii) Depth of water in cms
- iii) Width in mtrs.

(b) OTHERS: For all others including the rivers and canals the following are required.

- i) Start point
- ii) Turning points

(c) CONTOURS: The height of the contour, in steps of 50 mtr, relative height with the surrounding area taken at '0'.

All the start points and turning points are to be given as 4 figure grid reference. In between these 'Turning Points' the particular detail is approximated as a straight line, hence the points have to be chosen accordingly. While describing the details restriction is also made for the direction in which the next grid point exist. The next grid point has to be in one of the 8 cardinal direction i.e. N/NE/E/SE/S/SW/W/NW.

When the next grid point has been wrongly directed, a message is given i.e. 'going out of map area - direction

wrong'. This point could be recalculated and given.

All contours must be complete i.e. open contours might lead to wrong result hence not allowed.

Any number of such details can be described but each one has to be described separately. For example a river and its tributary will be described separately.

Once this programme is executed two files 'MAPDAT' and 'MAP' are made. They can be used for any subsequent exercise till another map, is defined in a similar manner.

BATTLE.PAS: The execution of this programme will simulate the tank battle. The following data is to be kept ready at the start of the exercise and given when asked.

(a) Type of tank used: Each tank has particular data associated with it for its armour and guns. The following 2 tanks have been catered for:

- i) Vijayanta
- ii) T-55

(b) Location of Troops: Location of 5 troops of a squadron of tanks in 4 figure grid reference.

(c) Time: The time of start of simulation of the exercise is to be given. Along with it the time

step to be used for the exercise is to be given. The minimum time step is calculated as 1 min. This time step can be changed during the execution of the programme as well.

- (d) Land marks: The land marks that are likely to be used during the exercise with their name (less than 12 chars without blanks) and its 4 figure grid reference. Any number of such land marks can be defined.

Once these details have been given the simulation of the exercise starts. There are various commands that can be given. There are basically 2 types of commands i.e. one that is addressed to a tank or otherwise.

The commands that could be addressed to a tank could be

- a) To report about certain attributes
- b) To move from one location to another
- c) To fire at a location or tank.

These are given as Appx. 'A'. The other commands that could be given to the simulator are

- (a) Help: To find the information regarding the commands addressable to the tanks.

(b) Check: The checking/changing of various status during the exercise like

- i) Land marks
- ii) Time step change
- iii) List of tanks on the move
- iv) Setting/Unsetting of map drawing.

(c) Freeze/Cont: This will freeze/unfreeze all the action part. This could be used at the time when some details have to be studied without change in status. 'Cont' will unfreeze the action.

(d) End: Used to terminate the programme.

Generally the following guidelines are to be used during interactive communication with the simulator.

- (a) All sentences or where possibility of a sentence exists, the reply has to end with a '.'.
- (b) A word is taken as 12 characters without blanks.
- (c) The delimiters between words are 'blank'/. /, .
- (d) All single word reply need not end with a '.'.
- (e) For a Yes/No type of dialogue, a simple 'Y' or 'N' could also be used.

The tank addressing is done by 'NO'. The 'NO' consists of 2 parts, Troop number followed by Tank number. Say there

are 5 troops and each troop having 3 tanks then TK 31 will mean Tank No. 1 of troop No. 3.

Normally map drawing will not be available. If this is required, then this will have to be set through CHECK. A one time map drawing is also available through this procedure.

CHAPTER IV

ALGORITHMS

In this chapter some algorithms will be discussed along with the assumptions/approximations that have been made.

4.1 Fire:

The procedure FIRE simulates the 'fire' part. The list of tanks that have been ordered to fire and details required is kept in a linked list of records FIRETAB. In each time step the number of shells that are to be fired is calculated, their effect analysed and reflected in the tank status of the affected tank. Once all the 'ordered' shells have been 'fired' by that tank then that record is deleted from the list.

The various fields in the record FIRETAB are as follows:

SOURCE TK:(INTEGER); Used for storing the number of the tank that is firing.

DEST TK :(INTEGER); Used to stores the number of the tank that is being fired upon. If it is '0' it indicates that firing is on a location.

SOURCE LOC: X,Y:(INTEGER): Stores the location co-ordinates of the tank firing the shells. Used for calculating distance and hit.

DEST LOC: X,Y:(INTEGER); Stores the location of tank being fired upon. Used for hit analysis and 'aiming'.

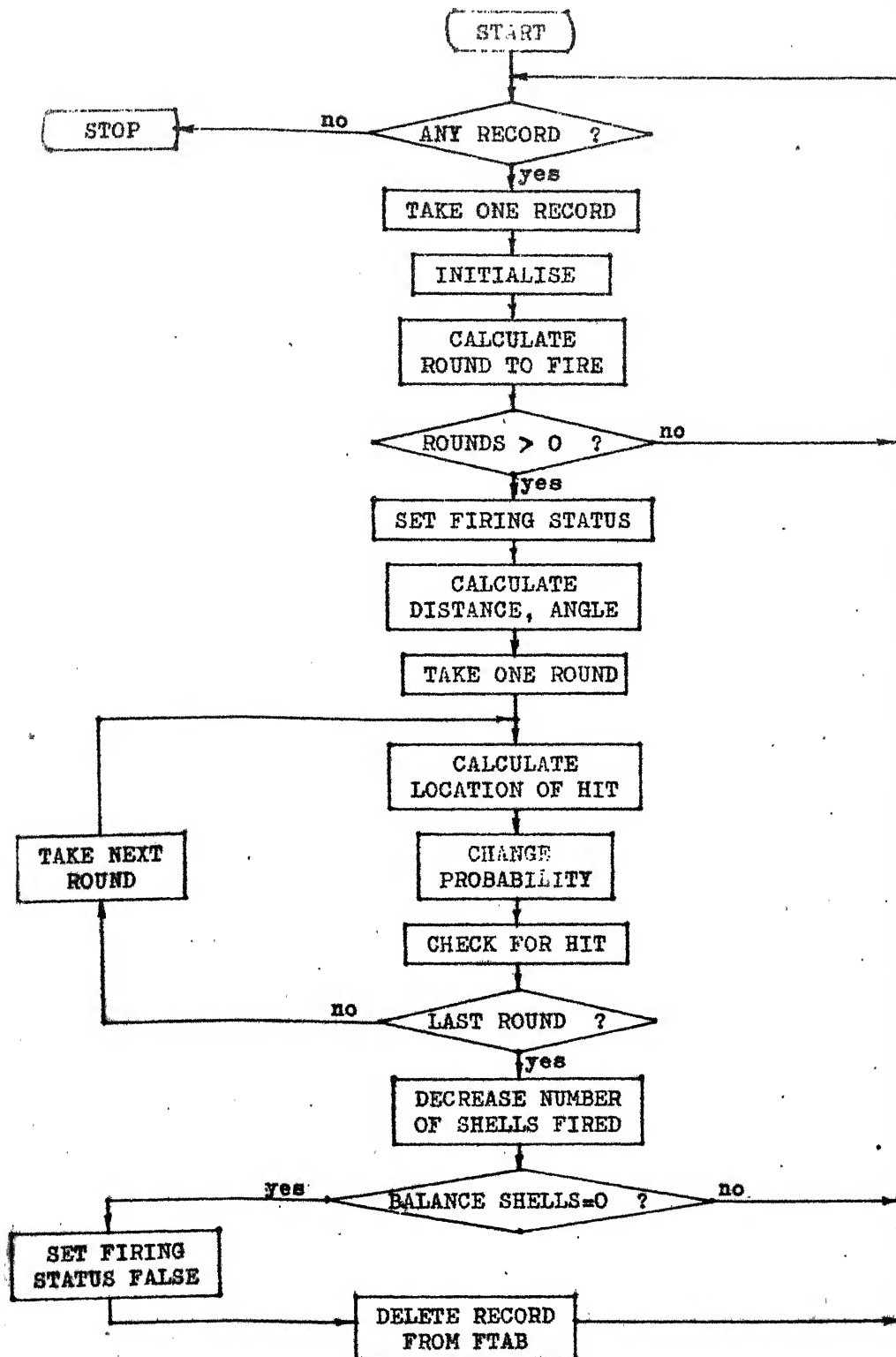
TOTNUM: (INTEGER); Gives the total number of shells that are left to be fired.

TIME: (INTEGER); This gives the load time i.e. time taken by the tank to initially start its first fire.

HIT PROB: (REAL); Gives the hit probability of the shell. Used for calculating the location of hit of the shell.

RATE : (0..15); This gives the number of shells that can be fired in a minute. This depends on the status of tank like moving etc.

ULINK, LLINK:(FPTR); Used to form a linked list of all the tanks that are firing and random deletion on completion of 'fire'.

FIRE

ALGORITHMSFIRE

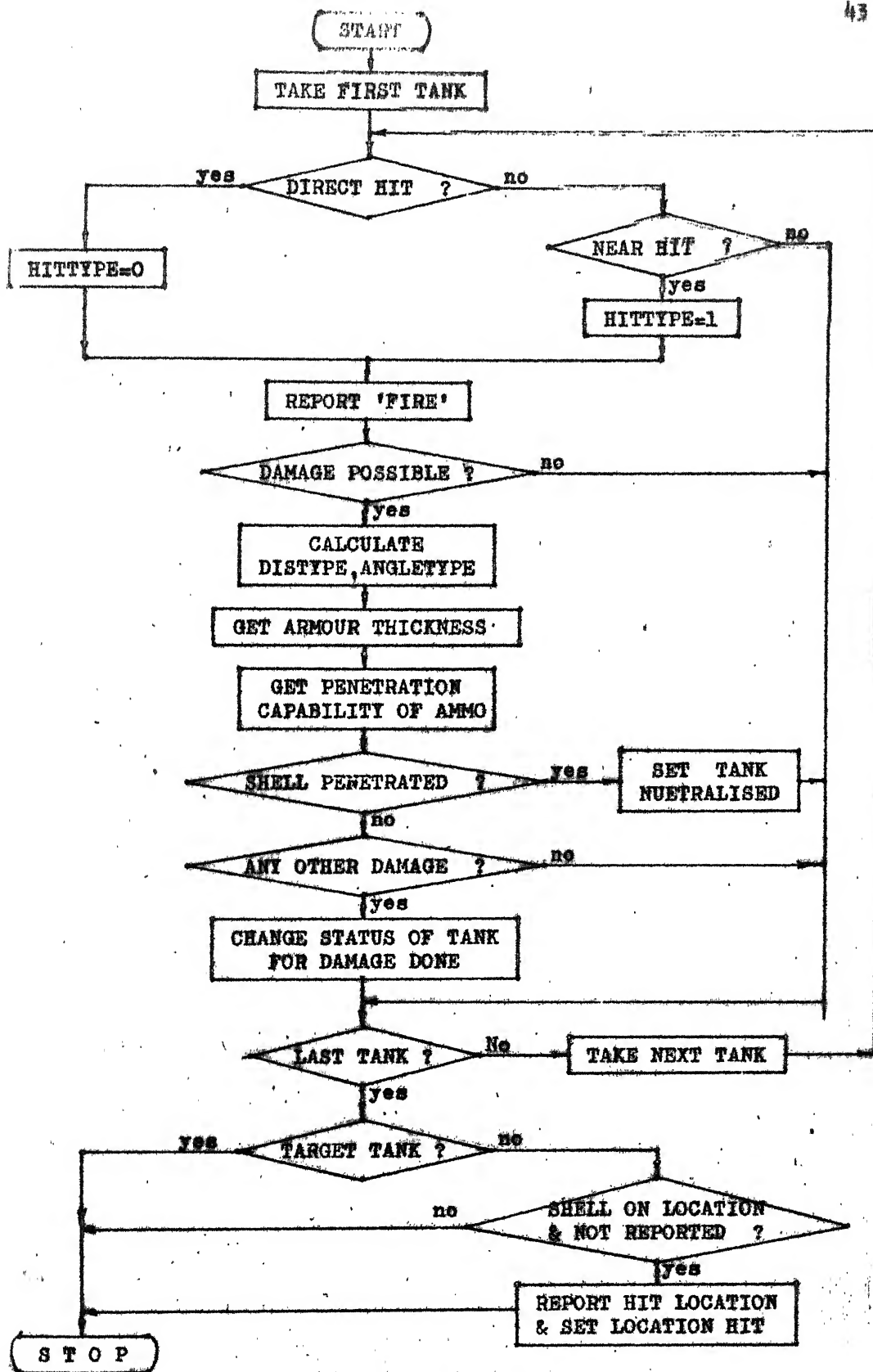
```
1. FOR EACH RECORD IN LIST FTAB DO
    BEGIN
    2. INITIALISE
    3. CALCULATE NUMBER OF ROUNDS TO BE FIRED IN THIS CYCLE
    4. IF NUMBER OF ROUNDS GREATER THAN ZERO THEN
        BEGIN
        5. SET STATUS OF THAT TANK TO FIRING
        6. CALCULATE DISTANCE & ANGLE TO TARGET
        7. FOR EACH ROUND DO
            BEGIN
            8. CALCULATE LOCATION OF HIT
            9. CHANGE PROBABILITY OF HIT
            10. CHECK HIT AND ANALYSE ITS EFFECT
            END
        11. DECREASE NUMBER OF SHELLS FROM BALANCE
        12. IF BALANCE OF SHELLS TO BE FIRED EQUALS ZERO THEN
            BEGIN
            13. SET FIRING STATUS TO FALSE
            14. DELETE THIS RECORD FROM FIRETAB
            END
        END
    END
END
```

END

CHECK HIT: Checks if any of the tanks have been hit directly or indirectly. If it is hit then calls for analysis for damage. Also checks, if the target is a location, then if it has been hit or not.

```
1. FOR EACH TANK DO
    BEGIN
        2. IF HIT LOCATION = TANK LOCATION THEN
            ANALYSE HIT FOR DIRECT HIT
        3. IF HIT LOCATION NEXT TO TANK LOCATION
            THEN ANALYSE HIT FOR INDIRECT HIT
    END
4. IF TARGET IS NOT TANK THEN
    BEGIN
        5. IF HIT LOCATION = TARGET LOCATION AND
            HAS NOT BEEN REPORTED THEN
            BEGIN
                6. REPORT LOCATION HIT
                7. SET THIS TO REPORTED
            END
    END
END
```

ANALYSE HIT: Reports target tank coming under fire and then analyses the hit for any damage it may have done and changes the status if required.



C H E C K H I T

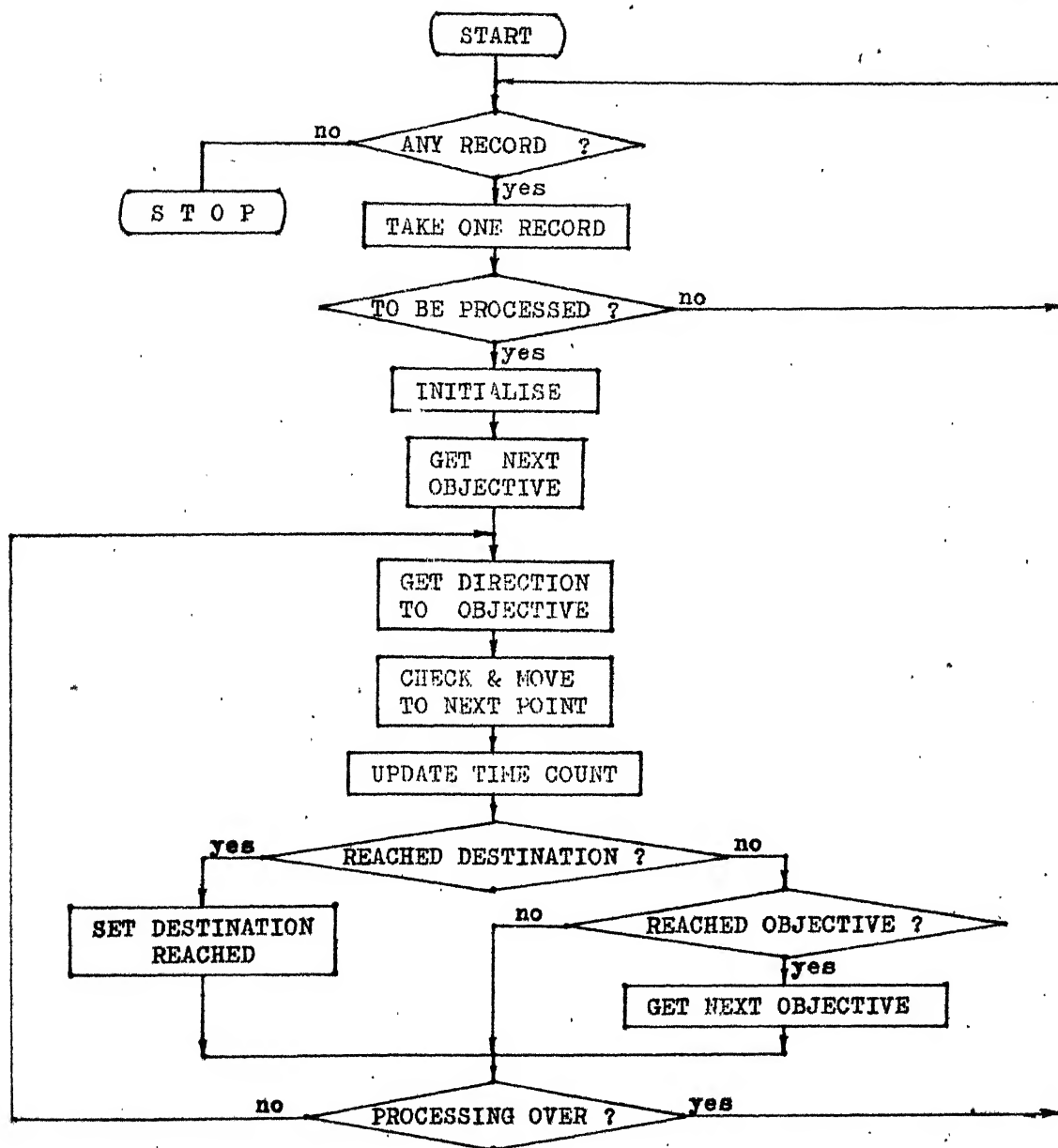
1. IF NOT REPORTED THEN REPORT COMING UNDER FIRE
 2. IF AMMUNITION IS NOT 'SMOKE' OR DISTANCE WITHIN RANGE
BEGIN
 3. CALCULATE DIST-TYPE & ANGLE OF HIT ON THE TANK
 4. GET ARMOUR THICKNESS AT THAT POINT
 5. IF THICKNESS \leq PENETRATING CAPABILITY
THEN SET TANK NUTRALISED
ELSE
 6. ANALYSE FOR EXTENT OF DAMAGE TO TANK AND CHANGE
STATUS ACCORDINGLY
- END

4.2 MOVE TANKS:

This procedure simulates the 'move' part. The details regarding all the tanks that have been ordered to 'move' are kept in a linked list of records in MOVTAB.

In each cycle, each tank in this list is moved for a time period of one time step unless it comes to a halt in between. During the move it 'jumps' from one grid point to another. Before going to the next point it checks for its topography and its possibility to move to that location.

If some obstacle is encountered then it takes action depending on the type of obstacle and command given. The change of status if any is reflected. Once the destination



MOVETANKS

is reached or has been neutralized or incapacitated permanently then this record is deleted from the move list MOVTAB.. The various fields in the record MOVTAB are

TANK NO: (0..99); The number of tank on the move.

SOURCE : X,Y:(INTEGER); The location of the starting point. X and Y coordinates of the tank.

DEST: X,Y: (INTEGER); The location it has to reach ultimately.

LOC: X,Y: (INTEGER); The present location where the tank is located.

ROUTE:ARRAY(1..10) OF CORD:X,Y:(INTEGER); Gives location of the intermediate points.

STATE:(BOOLEAN); Whether the tank is moving or stopped temporarily.

OBJECTIVE:(INTEGER): The total No. of intermediate points.

COURROBJECTIVE:(INTEGER); Present No. of the objective.

ALGORITHMS

MOVE

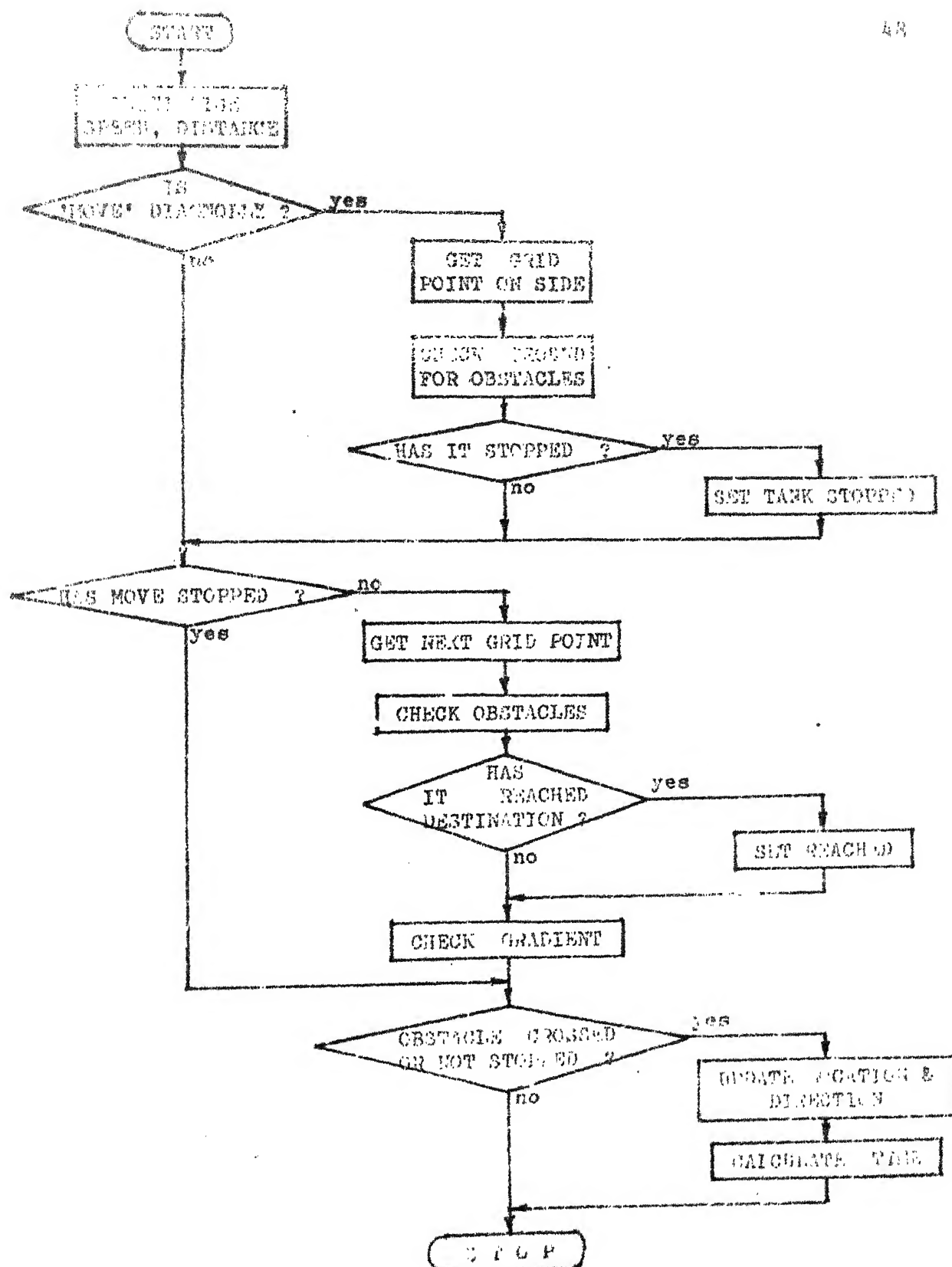
1. FOR EACH RECORD IN LIST DO
BEGIN


```
2. IF RECORD REQUIRES PROCESSING THEN
    BEGIN
    3. INITIALISE
    4. GET NEXT OBJECTIVE
        REPEAT
        5. GET DIRECTION TO OBJECTIVE
        6. COMPUTE TIME FOR MOVE TO NEXT POINT
            IF MOVE IS POSSIBLE
        7. INCREMENT TIME COUNT WITH CURRENT TIME
        8. IF REACHED DESTINATION, SET DESTINATION REACHED
        9. ELSE REACHED OBJECTIVE THEN GET
            NEW OBJECTIVE
        UNTIL REACHED DESTINATION OR FINISHED
            MOVE OR TIME STEP OVER
    END
END
```

COMPUTE TIME

This procedure calculates the next point that the tank is to be moved. Then checks for the type of ground that is there between the 2 points and the next point. If it can move to the next point then the following is calculated.

- a) Speed in this terrain
- b) Distance to the point



COMPUTE TIME

- c) Gradient between the points
- d) Fuel consumed

If it is not possible to move directly then checks if it can encounter this obstacle taking into consideration the following

- a) Type of obstacle
- b) Capability of the tank
- c) If water obstacle, then reports this and asks for orders. If ordered to cross then checks if it can, otherwise gets bogged.

COMPUTE TIME

1. INITIALISE DATA
2. IF TANK TRAVELLING DIAGONALLY THEN CHECK
GROUND IN BETWEEN FOR OBSTACLES
3. IF MOVE NOT FINISHED THEN
BEGIN
4. GET NEXT GRID POINT
5. CHECK GROUND FOR OBSTACLES
6. IF GRADIENT WITHIN LIMIT THEN
BEGIN
7. CALCULATE GRADIENT
8. CALCULATE SPEED CHANGE

9. FUEL CONSUMPTION CALCULATE

END

ELSE

10. STOP TANK AT LOCATION

END

11. IF TANK HAS NOT STOPPED OR HAS CROSSED OBSTACLE

BEGIN

12. MOVE TANK TO NEXT LOCATION

13. UPDATE DIRECTION OF TANK

14. CALCULATE TIME TAKEN TO REACH NEXT POINT

15. CALCULATE FUEL CONSUMED AND

DECREASE FROM BALANCE

END

4.3 Approximation/Assumptions:

For the simulation process some approximations and assumptions are made and these have been done keeping in view the realistic situation and its application on the computer. Some of these have been described in the succeeding paragraphs.

Distance between grid points is kept at 500 meters due to the following reasons:

- (a) Depiction of a large area of 20x20 Kms used for the mobility of the tank.

- (b) Decreasing the number of grid point for the same area thereby decreasing the memory requirements.
- (c) Resolution in graphic display due to limitation of size of display which is fixed.

Straight line approximation between points. In this case error is maximum within 500 mtr length because any number of turning points can be described. The limitation in direction restricted to only 8 is a constraint mainly for storage of data and computation simplicity. The deviation to some extent is acceptable for the exercise purpose.

Only six details like river, canal, road etc. have been included for the map description. Other details which do not have much bearing on the tank battle like anti-personnel mines, barbed wire fence, booby traps etc. have not been considered.

The minimum time step has been kept as 1 minute taking into consideration the maximum time taken by a tank to move from one point to another in the worst possible condition.

The Move and Fire operations are done serially one followed by the other and not parallel as it happens in real time. This is due to computer programme control flow being sequential.

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The 'shocked' tank is kept under shock only for one cycle of time but in actual practice this could be of variable length of time but is approximated as one cycle.

During the firing of shells, the rest of action is frozen as the time of flight is considered very small compared to movement during that period of time.

The height between 2 contours is kept constant throughout this area and height changes only from the next contour onwards.

4.4 Improvements:

In the 'MOVE' commands more general commands like move in formation, and deploy various tactical formation can be adopted and catered for.

Different type of firing tactics can be catered for. Here only 'Ranging' is used by SQUARE ROOT method.

More accurate analysis of hit of the shell could be done. In this, approximation is done upto an accuracy of ± 250 meters which may not be accurate in certain cases.

More details in the map description could be given like tracks, rough or forested area or undulating ground as found in deserts which provide cover to tanks or obstruct visibility could be described and used.

To give more realistic view, Air threat, Artillery and Anti-tank weapons could be incorporated in the simulations.

A combination of MOVE & FIRE tactics used in the case of providing covering fire for an attack could be included.

4.5 Time & Memory Considerations:

The simulator programme is written in Pascal language and implemented on system Dec 1090 computer. All the timings and memory requirement are corresponding to this system.

(a) Programme Storage

BATTLE.PAS	116K bytes
MAPRI.T.PAS	20K bytes

(b) Compilation data using

GPAS (Graphic Pascal)

Memory requirement = 105K bytes

Run time = 11 secs

(c) Programme Execution

- i) Time for initialisation, including
reading of map, tank locations, land marks
Time etc. = 10 secs (average).

- ii) Command Processing Times
 - Simulator command = 33 ms (average)
 - Tank commands = 16 ms (average)
- iii) Action Processing time = 26 ms (average)
- iv) Memory required during execution = 275K bytes (for programme example)

It must be noted that these timings and memory requirements will vary depending on the simulated exercise as dynamic storage and processing is used by the programme.

(d) Type of computer required: For the running of this programme any general purpose computer having the following facilities could be used.

- i) Memory of 64K
- ii) Terminals (TTY) for interactive usage
- iii) Graphic Terminal device (Tectronix display terminal) for the use of displaying of map if required.
- iv) Availability of Pascal graphics with its linking with GPGS.

CHAPTER V



GRAPHIC AIDS

The graphic aid used here for display purpose is Graphic Terminal (Tectronix display terminal) and the language used is Pascal (Graphics).

The size of display on this device is limited to physical size of 15 cms x 15 cms. On this is displayed an area of 20x20 kms divided into 40x40 grid points.

For easy referencing on the map '+' markers are displayed at an interval of 5 grid points i.e. distance of 2.5 kms. each.

The legend for the details represented with the markers that have been used are

- a) RIVER (double line) =
- b) CANAL (nabla) f
- c) ROAD (straight line) -
- d) MINEFIELD (cross) X
- e) MARSHY GROUND (Diamond) 
- f) GRASS/FIELD (Delta) 
- g) CONTOURS (dot) ..

The location of hit of a shell is displayed by a * at the location of hit. This is done only for those shells that

are fired in that cycle only. This is done by storing the hit location in a file FIREDT when the Fire procedure is executed. This data is used later by the programme DRAW MAP while drawing the map.

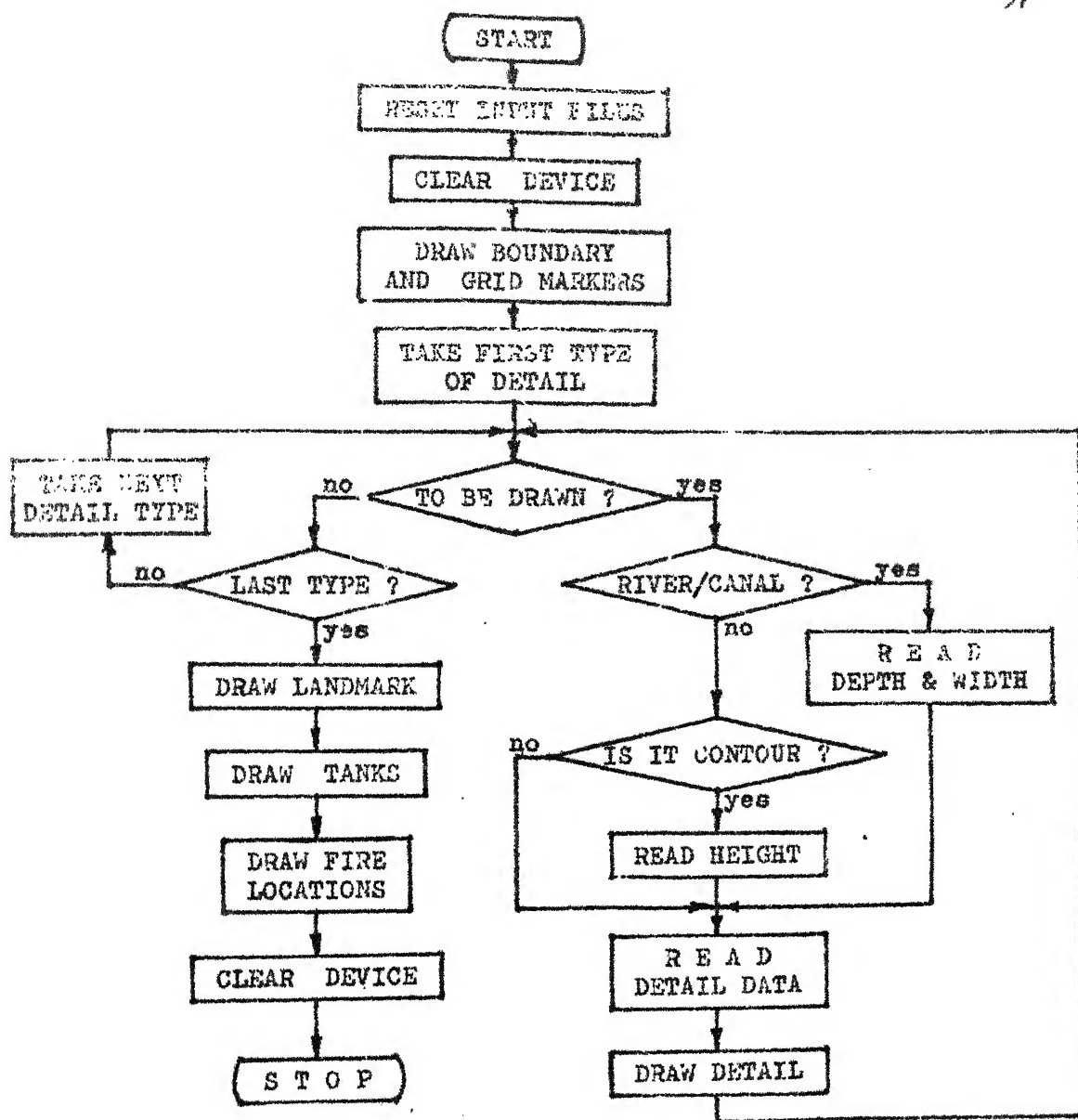
All land marks as described by the user is displayed on the terminal by the name at its location. Its exact location is given by starting character of the land mark name..

All tanks are displayed merely by their numbers i.e. Tank No. 3 of troop No. 1 is displayed as 13 on the displayed. The starting number gives the exact location of the tank.

The programme for Graphic Display is written in Pascal which does not at present provide all the facilities that are otherwise available in Fortran (GPGS). It is also handicapped by the lack of literature on it. Because of these restrictions graphic display is also restricted. This could be developed further as and when the Graphic Pascal becomes more powerful.

5.1 DRAW MAP:

This is the procedure used for drawing the map on the graphic terminal. It takes the input data from files MAPDAT, MAP and FIREDT. Apart from this the data for tanks location



DRAW MAP

is taken from Record TNKDAT and for land marks from LMTAB.
The flow chart for this is shown as Figure 6.

ALGORITHM

1. RESET INPUT FILES MAPDAT, MAP AND FIREDT
2. CLEAR GRAPHIC DEVICE
3. DRAW BOUNDARY AND GRID MARKERS
4. FOR EACH TYPE OF DETAIL DO
 BEGIN
 5. WHILE DETAILS OF THIS TYPE ARE TO BE DRAWN DO
 BEGIN
 6. IF DETAIL IS RIVER OR CANAL READ DEPTH & WIDTH
 7. ELSE IF DETAILS IS CONTOUR READ HEIGHT
 8. READ OTHER DATA REGARDING DETAIL
 9. DRAW DETAIL ON DEVICE
 END
 END
10. DRAW LANDMARKS
11. DRAW TANKS
12. DRAW FIRED SHELL LOCATIONS
13. CLEAR DEVICE IF SEEN

5.2 Test Exercise on Simulator:

For the purpose of demonstration, as to how this simulator could be used, a small test exercise is demonstrated

as follows. Assumptions made for this purpose and a narrative are given below. The aids used for this purpose are, the Hard Copy terminal for recording the interactive communication dialogues between the user and simulator and the 'plotter' to get the map output.

Exercise Background:

There are two states OWN DESH and ENEMY DESH, which have unfriendly relations. The NULLAH river which flows from loc 0127 to loc 3907 is the international boundary between them. Own Desh consists of troops 1,2 and 3 and Enemy Desh has troops 4 and 5. Their locations and various LANDMARKS are shown in MAP-1. Area HUT being a strategically important location Own Desh decides that it must capture it. It ventures to do this in the following manner.

(a) AIM: Troop 1 and Troop 2 to capture area HUT
by 042300 Hrs.

(b) PLAN: The plan to capture HUT is to be done
in 2 phases.

i) Phase 1: To cross river NULLAH and make a
bridge, Troop 1 in area TREE and Troop 2 in
area BRIDGE.

- ii) Phase 2: Troop 2 to move and capture area NODE to give support to Troop 1 for the capture of area HUT.
- (c) PROGRESS OF BATTLE: The course of events that take place during this operation are as follows:
 - i) Because of the increasing tension, Enemy Dosh sends TK 53 to 0723 and TK 42 to 3117 for observation.
 - ii) To divert attention Troop 1 and 2 fire smoke shells at loc 0823 and 3113 to give the impression that a river crossing and attack is being planned in this area.
 - iii) Falling for this TK 51 and TK 41 are sent by Enemy Dosh to locs 0822 and 3113.
 - iv) Troops 1 and 2 cross the river in area CROSS and BRIDGE respectively.
 - v) Troop 3 is brought up to Loc 1717 to give support to these troops.
 - iv) TK 52 moves to 1727 and TK 51 and TK 53 try and cross the NULLAH river to move from the back.

- vii) Troop 2 moves towards NODE and after softening it with fire assaults on it to capture it.
 - viii) Troop 1 after neutralising TK 52 moves to area HUT.
- (d) The activity recorded on the map's correspond to starting of the exercise (MAP-1), after completion of phase 1 (MAP-2) and after completion of the exercise (MAP-3).
- (e) The interactive dialogue used for this exercise is given as Appendix 'B'.

CHAPTER VI

CONCLUSION

A simulator for tactical exercise based on tank has been described here in reasonable detail. This simulator takes into account only a chosen set of factors and follows a specific set of rules built into it. Various constants such as those describing the accuracy of armament, the probability of neutralization and various kinds of hits are used by the simulator.

It is hoped that this simulator will form a logical extension of a sand model exercise, so that it provides more realistic details such that it gets close to real exercises in field. It will enable exercises in critical areas, such as enemy held territory or civilian territory in accessible for real exercises. By co-ordinating intelligence information with known topographical details of critical territories very effective familiarization with such areas can be ensured by simulator exercises.

The simulator goes beyond Armour battle and is very effective in training human decision making element in controlling complex operations, the outcome of which is primarily decided by equipment characteristics, fire power and tactics employed.

Man-machine communication is an important aspect which has been dealt with in this simulation. It is hoped that this will provide to the user how best to use this effectively to deal with a variety of command and control tasks.

It is considered that this simulator could be a useful training aid for Armoured Corp Officers in learning squadron level tactics. The simulator could be used both as a programmed teaching aid for minor tactics as well as training the squadron as a team.

6.1 Further Development:

A small operating system to simulate a squadron level battle to include the following features could be added.

- a) 2 rival squadrons are able to operate independently.
- b) Classification of messages, so that they are routed to various combination of leaders/tanks.
- c) An umpire who gets all messages and commands given by all originators.
- d) Partial display of the areas under their squadron to the Squadron commander and troop commanders.
- e) An element of chance to intercept messages of the opposing forces.

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APPENDIX A

APPENDIX A

COMMANDS AVAILABLE WITH OPTIONS

COMMAND:: = TK (TANK NUMBER) (REPORT PART)/(FIRE PART)/(MOVE PART).

REPORT PART:: = REPORT LOCATION

STATUS TK (TANK NUMBER)/\$ LOC (GRID REF)/\$

ENEMY

BALANCE AMMUNITION/FUEL HE/SMOKE/AP/ALL/\$

VISIBILITY TK(TANK NUMBER)/LOC (GRID REF)

FIRE PART:: = STOP FIRING

FIRE/SHOOT (NO) HE/AP/SMOKE SHELL(S) AT TK (TANK NUMBER)(DIRECTION)
LN (GRID REF)

MOVE PART:: = MOVE TO (LAND MARK) /\$

ROUTE (LAND MARKS)

(DISTANCE) MTR/METER/KM (DIRECTION)

OF (LAND MARK)

ROUTE (LAND MARK)

NOTE:

TANK NUMBER :: = TROOP NO. TANK NO.

DIRECTION :: = CLOCK DIRECTION/CARDINAL DIRECTION/DEGREE

CARDINAL DIRECTION:: = NORTH/N, NORTH EAST/NE etc.

LAND MARK :: = DEFINED LAND MARK/GRID REF

LAND MARKS :: = LAND MARK, LAND MARKS/\$

GRID REF :: = FOUR FIGURE GRID REFERENCE

THIS IS A PROGRAMME EXERCISE FOR TANK BATTLE AT SQUADRON LEVEL. YOU ARE REQUIRED TO TYPE IN COMMAND IN THE FORMAT SPECIFIED AND IT WILL BE EXECUTED. THE FOLLOWING POINTS NEED PARTICULAR ATTENTION:-

- 1 THE COMMAND MUST BE TYPED STARTING WITH <TK> OR OTHER COMMAND
- 2 THE COMMAND MUST END WITH <.>
- 3 IN CASE OF HELP TYPE <HELP<CMD> OR <HELP>
- 4 TO TERMINATE THE PROGRAMME TYPE <END.>
- 5 AFTER YOU HAVE WRITTEN YOUR COMMAND GIVE CARRIAGE RETURN
- 6 IF YOU WANT THESE COMMANDS TO TYPED THEN TYPE COMMAND <CHKPTS.

READY TO START NOW

PLEASE GIVE THE TYPE OF TANK USED -

if it is VIJAYANTA then type "v"

if it is T-55 then type "T"

type of tank :V

PLEASE GIVE THE LOCATION OF THE VARIOUS TROOPS OF YOUR SQUADRON

YOU ARE REQUIRED TO GIVE ONLY THE FOUR FIGURE GRID REFERENCE

TROOP NO 1:1519

TROOP NO 2:2511

TROOP NO 3:1511

TROOP NO 4:3133

TROOP NO 5:0531

IMPORTANT:note that the map details have been taken from your file ="MAP"

DO YOU WANT TO DEFINE LANDMARKS ?Y

TYPE IN LANDMARKS IN THE FOLLOWING FORMAT [<LM> <GR>.]

WHEN YOU HAVE FINISHED then type [FINISH.]

INPUT:HILL 1509.

INPUT:RDJN 2505.

INPUT:CROSS 1818.

INPUT:BRIDGE 2513.

INPUT:NULLAH 1021.

INPUT:TREE 1523.

INPUT:HUT 2129.

INPUT:NODE 2929.

INPUT:FIELD 1733.

INPUT:FINISH.

DO YOU WANT THE TABLE OF LANDMARKS ?N

DO YOU WANT TO CHANGE TIMESTEP? [BY DEFAULT IT IS TAKEN AS 1 MIN] :Y

PLEASE TYPE THE TIMESTEP IN FORMAT [<TIME> HR/MIN/SEC .] 13 MIN.
GIVE TIME OF START OF EXERCISE IN (HR,MIN) 4 FIGURES:1900

YOUR COMMAND:TK 42 MOVE TO 3117 ROUTE 3529,3519.

TIME:19: 3: 0

ROGER!

YOUR COMMAND:TK 53 MOVE TO 0723 ROUTE 0425.

TIME:19: 6: 0

ROGER!

TANK 4 2 REPORTING FROM LOCATION 35 24 CANAL OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:="

DIRECTION SOUTH WEST =>> NORTH EAST
APPROX WIDTH 50 METERS
APPROX DEPTH 25 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN a "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO
TANK 4 2 REPORTING > CANNOT NEGOTIATE THE CANAL - SIDE ARE VERY STEEP

TK 5 3 REPORTING REACHED DESTINATION 723
YOUR COMMAND:TK 13 FIRE 6 SMOKE SHELL LN 0823.

TIME:19: 9: 0

TK 13 REPORTS GIVING EFFECTIVE FIRE ON LN 823
YOUR COMMAND:TK 22 FIRE 6 SMOKE SHELL LN 3113.

TIME:19:12: 0

TANK 22 REPORTS GIVING EFFECTIVE FIRE ON LN 3113
YOUR COMMAND:TK 41 MOVE TO 2713 ROUTE 3527,3525,2725.

TIME:19:15: 0

ROGER!

YOUR COMMAND:TK 51 MOVE TO 0822 ROUTE 0425.

TIME:19:18: 0

ROGER!

TK 5 1 REPORTING REACHED DESTINATION 822
YOUR COMMAND:FREEZE.

TIME:19:21: 0

YOUR COMMAND:TK 13 MOVE TO 1922 ROUTE CROSS.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 12 MOVE TO 1624 ROUTE TREE.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 23 MOVE TO 2517.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 22 MOVE TO 2717 ROUTE BRIDGE.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 32 MOVE TO 1717 ROUTE 1910,2111.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 33 MOVE TO 1517 ROUTE 0911.

TIME:19:21: 0

ROGER!

YOUR COMMAND:TK 11 FIRE 8 HE SHELL LN 1123.

TIME:19:21: 0

YOUR COMMAND:TK 21 FIRE 8 HE SHELL LN 2717.

TIME:19:21: 0

YOUR COMMAND:CHECK.

TIME:19:21: 0

THE FOLLOWING CHECKS ARE POSSIBLE

LISTING LANDMARKS TYPE "L"
LISTING CURRENTLY MOVING TANKS-"T"
DRAWINGG THE MAP "M"
CHANGING TIMESTEP & TIME "C"
SETTING TO DRAW THE MAP-"S"
DELETING THE SET MAP DRAWING-"D"
RETURN-"R"

CHECK REQUIRED FOR:C

DO YOU WANT TO CHANGE TIME STEP? (BY DEFAULT IT IS TAKEN AS 1 MIN) :N

GIVE TIME OF START OF EXERCISE IN (HR,MIN) 4 FIGURES:1921
YOUR COMMAND:CONT,

TIME:19:21: 0

TANK 1 2 REPORTING FROM LOCATION 16 19 RIVER OBSTACLE AHEAD
with MAIN CHARACTERistics AS FOLLOWS:-

DIRECTION NORTH WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO

TANK 2 3 REPORTING FROM LOCATION 24 13 RIVER OBSTACLE AHEAD
with CHARACTERistics AS FOLLOWS:-

DIRECTION NORTH WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO

YOUR COMMAND:TK 52 MOVE TO 1728 ROUTE 0534,1734.

TIME:19:43: 0

ROGER!

TANK 11 REPORTS GIVING EFFECTIVE FIRE ON LN 1123
TANK 21 REPORTS GIVING EFFECTIVE FIRE ON LN 2717
YOUR COMMAND:TK 53 MOVE TO 0919 ROUTE 0420.

TIME:19:44: 0

ROGER!

TK 1 2 REPORTING REACHED DESTINATION 1624

TK 2 3 REPORTING REACHED DESTINATION 2517

TK 32 REPORTING REACHED DESTINATION 1717

TANK 5 3 REPORTING FROM LOCATION 7 23 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:=

DIRECTION NORTH WEST 420 SOUTH EAST

APPROX WIDTH 100 METERS

APPROX DEPTH 75 CMS

SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?

TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:90

TANK 11 REPORTS GIVING EFFECTIVE FIRE ON LN 1123

TANK 21 REPORTS GIVING EFFECTIVE FIRE ON LN 2717

YOUR COMMAND:TK 11 FIRE 6 AP SHELL AT TK 31.

TIME:19:45: 0

TK 3 3 REPORTING REACHED DESTINATION 1517

YOUR COMMAND:TK 23 FIRE 6 HE SHELL LN 2725.

TIME:19:46: 0

TK 1 3 REPORTING REACHED DESTINATION 1922

TK 2 2 REPORTING REACHED DESTINATION 2717

YOUR COMMAND:CONT.

TIME:19:47: 0

TANK 5 3 REPORTING > FROM LOCATION 620 TANK BOGGED DOWN IN MARSHY GR
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 2725
YOUR COMMAND:TK 23 REPORT VISIBILITY TK 41.

TIME:19:48: 0

TANKLOCATION 27 20
CANNOT SEE THAT DISTANCE AT NIGHT
IS NOT VISIBLE TO ME
YOUR COMMAND:TK 23 FIRE 4 AP SHELL LN 2722.

TIME:19:49: 0

YOUR COMMAND:TK 22 FIRE 4 HE SHELL AT TK 41.

TIME:19:50: 0

YOUR COMMAND:CONT.

TIME:19:51: 0

TK 4 1 REPORTING REACHED DESTINATION 2713

TK 5 2 REPORTING REACHED DESTINATION 1728
YOUR COMMAND:TK 41 FIRE 5 HE SHELL LN 2617.

TIME:19:52: 0

YOUR COMMAND:CONT.

TIME:19:53: 0

TANK 41 REPORTS GIVING EFFECTIVE FIRE ON LN 2617
YOUR COMMAND:TK 23 FIRE 6 HE SHELL AT TK 41.

TIME:19:54: 0

YOUR COMMAND:CONT.

TIME:19:55: 0

TANK 41 REPORTING! UNDER ENEMY HE FIRE FROM LOC 2517
TANK 23 REPORTS NUETRALISING ENEMY TK-> LOC 2713
YOUR COMMAND: FREEZE.

TIME:19:56: 0

YOUR COMMAND: TK 13 MOVE TO 1925.

TIME:19:56: 0

ROGER!

YOUR COMMAND: TK 12 MOVE TO 1927.

TIME:19:56: 0

ROGER!

YOUR COMMAND: TK 23 MOVE TO 2727.

TIME:19:56: 0

ROGER!

YOUR COMMAND: TK 22 MOVE TO 3133 ROUTE 2532.

TIME:19:56: 0

ROGER!

YOUR COMMAND: TK 32 FIRE 10 HE SHELL LN 0923.

TIME:19:56: 0

YOUR COMMAND: TK 11 MOVE TO 1923.

TIME:19:56: 0

ROGER!

YOUR COMMAND: CONT.

TIME:19:56: 0

TANK 1 2 REPORTING FROM LOCATION 16 24 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:=

	DIRECTION	NORTH	=>>	SOUTH
APPROX WIDTH	25	METERS		
APPROX DEPTH	25	CMS		
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?				
TYPE IN A "C" FOR CHANGING COURSR OR A "GO" TO CONTINUE:GO				

TANK 1 1 REPORTING FROM LOCATION 15 19 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:-

DIRECTION NORTH WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS
APPROX DEPTH 75 CMS
SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:C
TANK ALREADY ON MOVE. DO YOU WANT TO CHANGE STATUS ?Y
FOR CHANGING ONLY DESTINATION TYPE "D"
FOR CHANGING ONLY ROUTE TYPE "R"
FOR COMPLETE CHANGING "C"
FOR RETURN WITHOUT CHANGING "W"
TYPE OF CHANGE REQUIRED ?D
NEW DESTINATION:1525
YOUR COMMAND:UDMI.

TIME:19:57: 0

TK 1 2 REPORTING REACHED DESTINATION 1927

TANK 1 1 REPORTING FROM LOCATION 15 20 RIVER OBSTACLE AHEAD
with MAIN CHARACTEREstics AS FOLLOWS:-

DIRECTION WEST =>> SOUTH EAST
APPROX WIDTH 100 METERS

APPROX DEPTH 75 CMS

SHOULD I NEGOTIATE THE OBSTACLE or CHANGE COURSE ?
TYPE IN A "C" FOR CHANGING COURSE OR A "GO" TO CONTINUE:GO
TANK 32 REPORTS GIVING EFFECTIVE FIRE ON LN 923
YOUR COMMAND:TK 13 FIRE 4 AP SHELL AT TK 52.

TIME:19:58: 0

TK 1 3 REPORTING REACHED DESTINATION 1925

TANK 32 REPORTS GIVING EFFECTIVE FIRE ON LN 0923
YOUR COMMAND:TK 52 FIRE 4 HE SHELL LN 1725.

TIME:19:59: 0

TK 1 1 REPORTING REACHED DESTINATION 1525

TANK 52 REPORTING!UNDER ENEMY AP FIRE FROM LOC 1924
YOUR COMMAND:TK 21 MOVE 2 KM NORTH.

TIME:20: 0: 0

ROGER!

TANK 52 REPORTS GIVING EFFECTIVE FIRE ON LN 1725
YOUR COMMAND:TK 23 FIRE 8 HE SHELL LN 3133.

TIME:20: 1: 0

TK 2 3 REPORTING REACHED DESTINATION 2727

YOUR COMMAND:TK 12 FIRE 4 AP SHELL LN 1728.

TIME:20: 2: 0

TANK 43 REPORTING!UNDER ENEMY HE FIRE FROM LOC 2625
TANK 23 REPORTS NUETRALISING ENEMY TK-> LOC 3032
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 3133
YOUR COMMAND:CONT.

TIME:20: 3: 0

TK 2 1 REPORTING REACHED DESTINATION 2515

TANK 43 REPORTING!UNDER ENEMY HE FIRE FROM LOC 2625
TANK 23 REPORTS GIVING EFFECTIVE FIRE ON LN 3133

TANK 52 REPORTING!UNDER ENEMY AP FIRE FROM LOC 1927
TANK 12 REPORTS GIVING EFFECTIVE FIRE ON LN 1728
YOUR COMMAND:TK 22 REPORT LOCATION.

TIME:20: 4: 0

TANK 2 OF TROOP 2 REPORTING

LOCATION	X	Y
	25	31

YOUR COMMAND:TK 23 MOVE TO 3133.

TIME:20: 5: 0

ROGER!

TANK 2 3 REPORTING > FROM LOCATION 2828
TANK HAS RUN INTO ENEMY HINEFEILD!!
YOUR COMMAND:TK 13 FIRE 4 SMOKE SHELL LN 2129.

TIME:20: 6: 0

YOUR COMMAND:TK 12 MOVE TO 2130.

TIME:20: 7: 0

ROGER!

TK 2 2 REPORTING REACHED DESTINATION 3133

TANK 13 REPORTS GIVING EFFECTIVE FIRE ON LN 2129
YOUR COMMAND:TK 13 MOVE TO 2128.

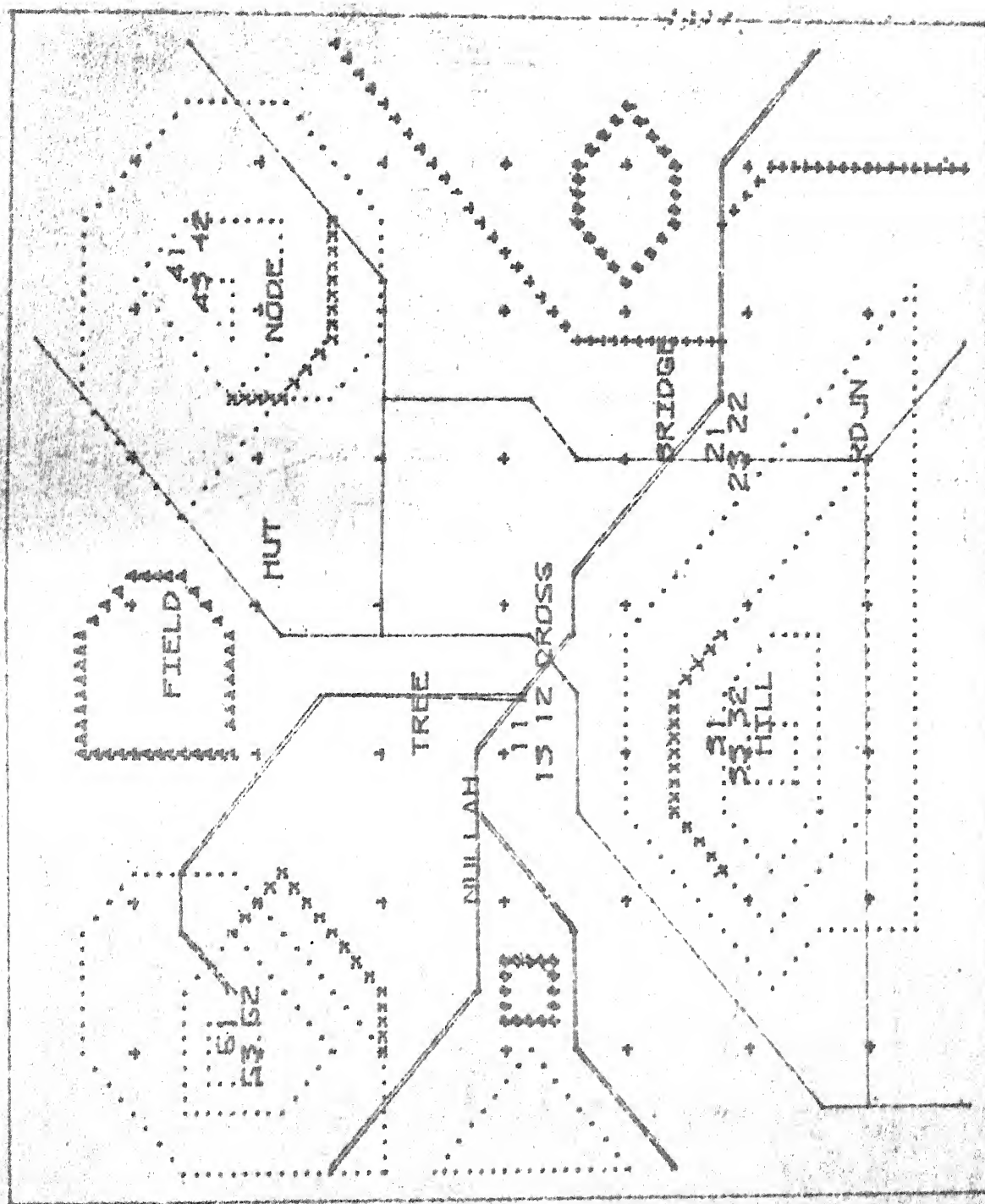
TIME:20: 8: 0

ROGER!

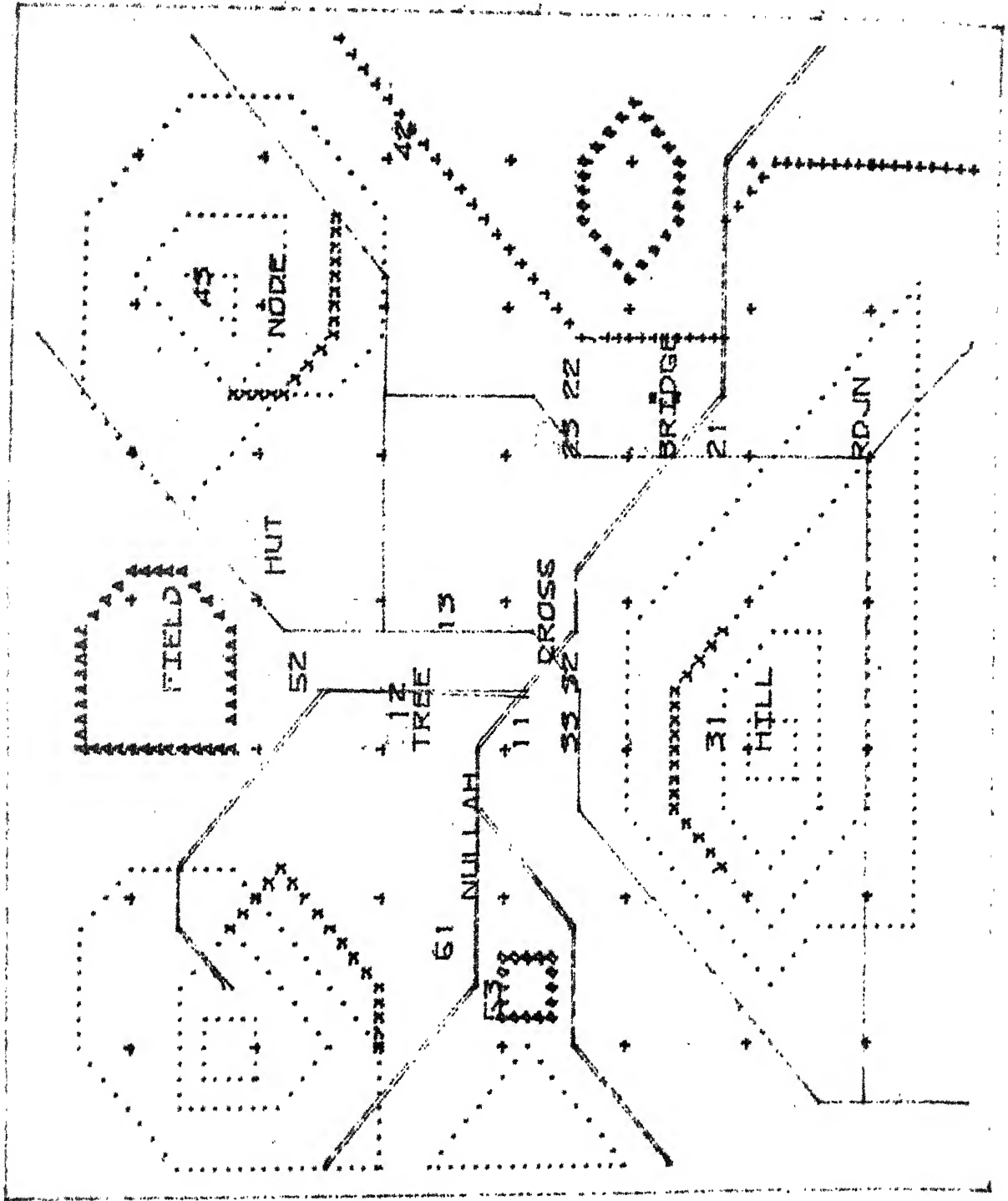
TK 1 3 REPORTING REACHED DESTINATION 2128
YOUR COMMAND:CONT.

TIME:20: 9: 0

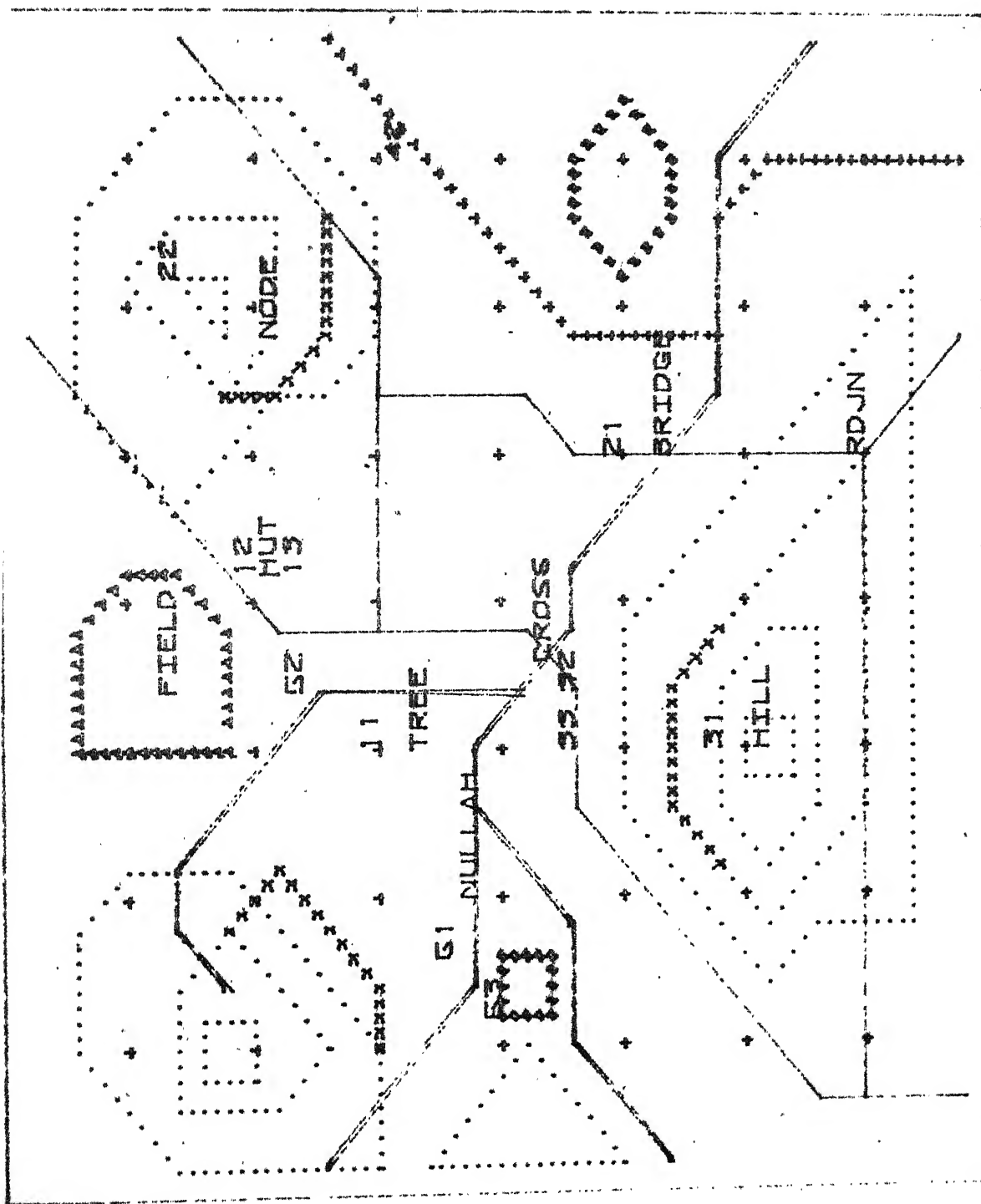
TK 1 2 REPORTING REACHED DESTINATION 2130
YOUR COMMAND:END.



MAP - 1



MAP-2



MAP - 3

APPENDIX C


```

00570 DEPRESSION:=integer(*MAXIMUM DEPRESSION POSSIBLE +/-1#)
00580 end;
00590 LPPR:=packed array[1..2]of char;
00600 LPPR:=packed array[1..2]of char;
00610 LPPR:=0.;
00620 LPPR:=LPPR+LPPR;
00630 LPPR:=LPPR-LPPR;
00640 LPPR:=LPPR-LPPR;
00650 VAL:=1, VAL:=2; integer
00660 end;
00670 LPPR:=packed array[1..2]of char;
00680 LPPR:=LPPR;
00690 LPPR:=LPPR;
00700 LPPR:=LPPR;
00710 LPPR:=LPPR;
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01080 LPPR:=LPPR;
01090 LPPR:=LPPR;
01100 LPPR:=LPPR;
01110 LPPR:=LPPR;
01120 LPPR:=LPPR;

```


[illegible]

[illegible]

[illegible]

```

IS NUMBER:=false;
if TESTNUMBER then
  begin
    SUBSTR(5):=SUBSTR(1,43) YOU LIKE 10 SUBSTITUTE 143 NUMBER 220;
    BREAK; READCH;
  if CH=y, then
    begin
      SUBSTR(1):=YOUR NEW NUMBER:; BREAK; READWORD; 14423
    end
  end
end

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[illegible]

```

J:Integer;
var
  J:Integer;
  L:0..WRITEFUNC(TTY)

```

* * * * *

(SINCE CHECKS ARE)

* * * * *

```
if not y: then yes:=true
if not y: then yes:=false
```

[illegible][illegible]

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[illegible]

```
procedure CALCULATE_DIST(x1,y1,x2,y2);
begin
    if x1=x2 and y1=y2 then DIST:=0;
    else DIST:=INTERVAL(x1,y1,x2,y2) end;
```

Vertical

[illegible]

[illegible]


```

05610 procedure CALCVXVY(X:var X,Y:integer; direction:range);
05620 (* gives the direction for the present location in (X,Y)
05630 if gives the next tripoint in (X,Y) *)
05640
05650 begin
05660 case direction of
05670 1: vi:=v+1;
05680 2: vi:=v+1;
05690 3: vi:=v+1;
05700 4: vi:=v+1;
05710 5: vi:=v+1;
05720 6: vi:=v+1;
05730 7: vi:=v+1;
05740 8: vi:=v+1;
05750 9: vi:=v+1;
05760 10: vi:=v+1;
05770 11: vi:=v+1;
05780 12: vi:=v+1;
05790 13: vi:=v+1;
05800 14: vi:=v+1;
05810 15: vi:=v+1;
05820 16: vi:=v+1;
05830 17: vi:=v+1;
05840 18: vi:=v+1;
05850 19: vi:=v+1;
05860 20: vi:=v+1;
05870 21: vi:=v+1;
05880 22: vi:=v+1;
05890 23: vi:=v+1;
05900 24: vi:=v+1;
05910 25: vi:=v+1;
05920 26: vi:=v+1;
05930 27: vi:=v+1;
05940 28: vi:=v+1;
05950 29: vi:=v+1;
05960 30: vi:=v+1;
05970 31: vi:=v+1;
05980 32: vi:=v+1;
05990 33: vi:=v+1;
06000 34: vi:=v+1;
06010 35: vi:=v+1;
06020 36: vi:=v+1;
06030 37: vi:=v+1;
06040 38: vi:=v+1;
06050 39: vi:=v+1;
06060 40: vi:=v+1;
06070 41: vi:=v+1;
06080 42: vi:=v+1;
06090 43: vi:=v+1;
06100 44: vi:=v+1;
06110 45: vi:=v+1;
06120 46: vi:=v+1;
06130 47: vi:=v+1;
06140 48: vi:=v+1;
06150 49: vi:=v+1;
06160 50: vi:=v+1;

```



```

06730 UNTIL ((CHR='V')OR(C1='V'))
06740 PRINTLN(PHY,V01)
06750 PRINTLN(PHY,V01)
06760 FOR J:=1 TO 5 DO
06770 BEGIN
06780   PRINTLN(PHY,V01)
06790   PRINTLN(PHY,V01)
06800   ADD:=1
06810   FOR I:=1 TO 3 DO
06820     WITH J+2*V01,I DO
06830       PRINTLN(PHY,V01)
06840       PRINTLN(PHY,V01)
06850       PRINTLN(PHY,V01)
06860       IF I=1 THEN
06870         WITH MAPCORD.X:=X;MAPCORD.Y:=Y;
06880         BEGIN
06890           ELSE
06900             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06910             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06920             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06930             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06940             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06950             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06960             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06970             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06980             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
06990             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07000             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07010             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07020             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07030             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07040             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07050             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07060             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07070             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07080             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07090             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07100             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07110             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07120             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07130             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07140             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07150             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07160             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07170             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07180             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07190             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07200             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07210             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07220             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07230             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07240             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07250             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07260             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07270             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);
07280             WITH MAPCORD.X:=X+ADD;MAPCORD.Y:=Y-1;ADD:=ADD*(-1);

```

```

07290 then
07300   TIMESEC:=TIMESEC+TIMESER;
07310   if TIMESER>=60 then
07320     begin
07330       TIMESER:=TIMESER-TIMESER;
07340       TIMESER:=TIMESER+TIMESER;
07350       TIMESER:=TIMESER+TIMESER;
07360       TIMESER:=TIMESER+TIMESER;
07370       TIMESER:=TIMESER+TIMESER;
07380       TIMESER:=TIMESER+TIMESER;
07390       TIMESER:=TIMESER+TIMESER;
07400       TIMESER:=TIMESER+TIMESER;
07410       TIMESER:=TIMESER+TIMESER;
07420       TIMESER:=TIMESER+TIMESER;
07430       TIMESER:=TIMESER+TIMESER;
07440       TIMESER:=TIMESER+TIMESER;
07450       TIMESER:=TIMESER+TIMESER;
07460       TIMESER:=TIMESER+TIMESER;
07470       TIMESER:=TIMESER+TIMESER;
07480       TIMESER:=TIMESER+TIMESER;
07490       TIMESER:=TIMESER+TIMESER;
07500       TIMESER:=TIMESER+TIMESER;
07510       TIMESER:=TIMESER+TIMESER;
07520       TIMESER:=TIMESER+TIMESER;
07530       TIMESER:=TIMESER+TIMESER;
07540       TIMESER:=TIMESER+TIMESER;
07550       TIMESER:=TIMESER+TIMESER;
07560       TIMESER:=TIMESER+TIMESER;
07570       TIMESER:=TIMESER+TIMESER;
07580       TIMESER:=TIMESER+TIMESER;
07590       TIMESER:=TIMESER+TIMESER;
07600       TIMESER:=TIMESER+TIMESER;
07610       TIMESER:=TIMESER+TIMESER;
07620       TIMESER:=TIMESER+TIMESER;
07630       TIMESER:=TIMESER+TIMESER;
07640       TIMESER:=TIMESER+TIMESER;
07650       TIMESER:=TIMESER+TIMESER;
07660       TIMESER:=TIMESER+TIMESER;
07670       TIMESER:=TIMESER+TIMESER;
07680       TIMESER:=TIMESER+TIMESER;
07690       TIMESER:=TIMESER+TIMESER;
07700       TIMESER:=TIMESER+TIMESER;
07710       TIMESER:=TIMESER+TIMESER;
07720       TIMESER:=TIMESER+TIMESER;
07730       TIMESER:=TIMESER+TIMESER;
07740       TIMESER:=TIMESER+TIMESER;
07750       TIMESER:=TIMESER+TIMESER;
07760       TIMESER:=TIMESER+TIMESER;
07770       TIMESER:=TIMESER+TIMESER;
07780       TIMESER:=TIMESER+TIMESER;
07790       TIMESER:=TIMESER+TIMESER;
07800       TIMESER:=TIMESER+TIMESER;
07810       TIMESER:=TIMESER+TIMESER;
07820       TIMESER:=TIMESER+TIMESER;
07830       TIMESER:=TIMESER+TIMESER;
07840       TIMESER:=TIMESER+TIMESER;

```

```

07850 *****
07855 procedure CALLANGLEX(I:integer); *****
07860 *****
07865 begin *****
07870 if angle <= 0.42 then DIRECTION:=ABS(BASE-2) *****
07875 else *****
07880 if angle <= 2.35 then DIRECTION:=ABS(BASE-3) *****
07885 else DIRECTION:=1 *****
07890 end; *****
07895
07900 begin *****
07905 XDISP:=X2-X1; *****
07910 YDISP:=Y2-Y1; *****
07915 if XDISP=0 then *****
07920 if YDISP > 0 then DIRECTION:=0 *****
07925 else *****
07930 if DIRECTION:=4 *****
07935 else *****
07940 begin *****
07945 XDISP:=ABS(YDISP/XDISP); *****
07950 if YDISP > 0 then *****
07955 if XDISP > 0 then CALLANGLEX(0) *****
07960 else *****
07965 if XDISP > 0 then CALLANGLEX(8) *****
07970 else *****
07975 end *****
07980
07985 *****
07990 procedure FILLOPOGRAPHY; *****
07995 (* takes the details described earlier from file input and stores it for use *) *****
08000 (* when this is completed a note to this effect is given on PLY *) *****
08005 type *****
08010 SPLITARRAY=packed array[1..210 of 0..99; *****
08015
08020 var *****
08025 WIDTH, HEIGHT, DEPTH, L, DEGREE: integer; *****
08030 CUR1, CUR2: integer; *****
08035 FIXECCORD: packed array[1..101 of char; *****
08040 FIRSTCOORD1, FIRSTCOORD2, FIRSTCOORD3, FIRSTCOORD4, FIRSTCOORD5, *****
08045 FIRSTCOORD6, FIRSTCOORD7, FIRSTCOORD8, FIRSTCOORD9, FIRSTCOORD10, *****
08050 FIRSTCOORD11, FIRSTCOORD12, FIRSTCOORD13, FIRSTCOORD14, FIRSTCOORD15, *****
08055 FIRSTCOORD16, FIRSTCOORD17, FIRSTCOORD18, FIRSTCOORD19, FIRSTCOORD20, *****
08060 FIRSTCOORD21, FIRSTCOORD22, FIRSTCOORD23, FIRSTCOORD24, FIRSTCOORD25, *****
08065 FIRSTCOORD26, FIRSTCOORD27, FIRSTCOORD28, FIRSTCOORD29, FIRSTCOORD30, *****
08070 FIRSTCOORD31, FIRSTCOORD32, FIRSTCOORD33, FIRSTCOORD34, FIRSTCOORD35, *****
08075 FIRSTCOORD36, FIRSTCOORD37, FIRSTCOORD38, FIRSTCOORD39, FIRSTCOORD40, *****
08080 FIRSTCOORD41, FIRSTCOORD42, FIRSTCOORD43, FIRSTCOORD44, FIRSTCOORD45, *****
08085 FIRSTCOORD46, FIRSTCOORD47, FIRSTCOORD48, FIRSTCOORD49, FIRSTCOORD50, *****
08090 FIRSTCOORD51, FIRSTCOORD52, FIRSTCOORD53, FIRSTCOORD54, FIRSTCOORD55, *****
08095 FIRSTCOORD56, FIRSTCOORD57, FIRSTCOORD58, FIRSTCOORD59, FIRSTCOORD60, *****
08100 FIRSTCOORD61, FIRSTCOORD62, FIRSTCOORD63, FIRSTCOORD64, FIRSTCOORD65, *****
08105 FIRSTCOORD66, FIRSTCOORD67, FIRSTCOORD68, FIRSTCOORD69, FIRSTCOORD70, *****
08110 FIRSTCOORD71, FIRSTCOORD72, FIRSTCOORD73, FIRSTCOORD74, FIRSTCOORD75, *****
08115 FIRSTCOORD76, FIRSTCOORD77, FIRSTCOORD78, FIRSTCOORD79, FIRSTCOORD80, *****
08120 FIRSTCOORD81, FIRSTCOORD82, FIRSTCOORD83, FIRSTCOORD84, FIRSTCOORD85, *****
08125 FIRSTCOORD86, FIRSTCOORD87, FIRSTCOORD88, FIRSTCOORD89, FIRSTCOORD90, *****
08130 FIRSTCOORD91, FIRSTCOORD92, FIRSTCOORD93, FIRSTCOORD94, FIRSTCOORD95, *****
08135 FIRSTCOORD96, FIRSTCOORD97, FIRSTCOORD98, FIRSTCOORD99, FIRSTCOORD100, *****
08140 FIRSTCOORD101, FIRSTCOORD102, FIRSTCOORD103, FIRSTCOORD104, FIRSTCOORD105, *****
08145 FIRSTCOORD106, FIRSTCOORD107, FIRSTCOORD108, FIRSTCOORD109, FIRSTCOORD110, *****
08150 FIRSTCOORD111, FIRSTCOORD112, FIRSTCOORD113, FIRSTCOORD114, FIRSTCOORD115, *****
08155 FIRSTCOORD116, FIRSTCOORD117, FIRSTCOORD118, FIRSTCOORD119, FIRSTCOORD120, *****
08160 FIRSTCOORD121, FIRSTCOORD122, FIRSTCOORD123, FIRSTCOORD124, FIRSTCOORD125, *****
08165 FIRSTCOORD126, FIRSTCOORD127, FIRSTCOORD128, FIRSTCOORD129, FIRSTCOORD130, *****
08170 FIRSTCOORD131, FIRSTCOORD132, FIRSTCOORD133, FIRSTCOORD134, FIRSTCOORD135, *****
08175 FIRSTCOORD136, FIRSTCOORD137, FIRSTCOORD138, FIRSTCOORD139, FIRSTCOORD140, *****
08180 FIRSTCOORD141, FIRSTCOORD142, FIRSTCOORD143, FIRSTCOORD144, FIRSTCOORD145, *****
08185 FIRSTCOORD146, FIRSTCOORD147, FIRSTCOORD148, FIRSTCOORD149, FIRSTCOORD150, *****
08190 FIRSTCOORD151, FIRSTCOORD152, FIRSTCOORD153, FIRSTCOORD154, FIRSTCOORD155, *****
08195 FIRSTCOORD156, FIRSTCOORD157, FIRSTCOORD158, FIRSTCOORD159, FIRSTCOORD160, *****
08200 FIRSTCOORD161, FIRSTCOORD162, FIRSTCOORD163, FIRSTCOORD164, FIRSTCOORD165, *****
08205 FIRSTCOORD166, FIRSTCOORD167, FIRSTCOORD168, FIRSTCOORD169, FIRSTCOORD170, *****
08210 FIRSTCOORD171, FIRSTCOORD172, FIRSTCOORD173, FIRSTCOORD174, FIRSTCOORD175, *****
08215 FIRSTCOORD176, FIRSTCOORD177, FIRSTCOORD178, FIRSTCOORD179, FIRSTCOORD180, *****
08220 FIRSTCOORD181, FIRSTCOORD182, FIRSTCOORD183, FIRSTCOORD184, FIRSTCOORD185, *****
08225 FIRSTCOORD186, FIRSTCOORD187, FIRSTCOORD188, FIRSTCOORD189, FIRSTCOORD190, *****
08230 FIRSTCOORD191, FIRSTCOORD192, FIRSTCOORD193, FIRSTCOORD194, FIRSTCOORD195, *****
08235 FIRSTCOORD196, FIRSTCOORD197, FIRSTCOORD198, FIRSTCOORD199, FIRSTCOORD200, *****
08240 FIRSTCOORD201, FIRSTCOORD202, FIRSTCOORD203, FIRSTCOORD204, FIRSTCOORD205, *****
08245 FIRSTCOORD206, FIRSTCOORD207, FIRSTCOORD208, FIRSTCOORD209, FIRSTCOORD210, *****
08250 FIRSTCOORD211, FIRSTCOORD212, FIRSTCOORD213, FIRSTCOORD214, FIRSTCOORD215, *****
08255 FIRSTCOORD216, FIRSTCOORD217, FIRSTCOORD218, FIRSTCOORD219, FIRSTCOORD220, *****
08260 FIRSTCOORD221, FIRSTCOORD222, FIRSTCOORD223, FIRSTCOORD224, FIRSTCOORD225, *****
08265 FIRSTCOORD226, FIRSTCOORD227, FIRSTCOORD228, FIRSTCOORD229, FIRSTCOORD230, *****
08270 FIRSTCOORD231, FIRSTCOORD232, FIRSTCOORD233, FIRSTCOORD234, FIRSTCOORD235, *****
08275 FIRSTCOORD236, FIRSTCOORD237, FIRSTCOORD238, FIRSTCOORD239, FIRSTCOORD240, *****
08280 FIRSTCOORD241, FIRSTCOORD242, FIRSTCOORD243, FIRSTCOORD244, FIRSTCOORD245, *****
08285 FIRSTCOORD246, FIRSTCOORD247, FIRSTCOORD248, FIRSTCOORD249, FIRSTCOORD250, *****
08290 FIRSTCOORD251, FIRSTCOORD252, FIRSTCOORD253, FIRSTCOORD254, FIRSTCOORD255, *****
08295 FIRSTCOORD256, FIRSTCOORD257, FIRSTCOORD258, FIRSTCOORD259, FIRSTCOORD260, *****
08300 FIRSTCOORD261, FIRSTCOORD262, FIRSTCOORD263, FIRSTCOORD264, FIRSTCOORD265, *****
08305 FIRSTCOORD266, FIRSTCOORD267, FIRSTCOORD268, FIRSTCOORD269, FIRSTCOORD270, *****
08310 FIRSTCOORD271, FIRSTCOORD272, FIRSTCOORD273, FIRSTCOORD274, FIRSTCOORD275, *****
08315 FIRSTCOORD276, FIRSTCOORD277, FIRSTCOORD278, FIRSTCOORD279, FIRSTCOORD280, *****
08320 FIRSTCOORD281, FIRSTCOORD282, FIRSTCOORD283, FIRSTCOORD284, FIRSTCOORD285, *****
08325 FIRSTCOORD286, FIRSTCOORD287, FIRSTCOORD288, FIRSTCOORD289, FIRSTCOORD290, *****
08330 FIRSTCOORD291, FIRSTCOORD292, FIRSTCOORD293, FIRSTCOORD294, FIRSTCOORD295, *****
08335 FIRSTCOORD296, FIRSTCOORD297, FIRSTCOORD298, FIRSTCOORD299, FIRSTCOORD300, *****
08340 FIRSTCOORD301, FIRSTCOORD302, FIRSTCOORD303, FIRSTCOORD304, FIRSTCOORD305, *****
08345 FIRSTCOORD306, FIRSTCOORD307, FIRSTCOORD308, FIRSTCOORD309, FIRSTCOORD310, *****
08350 FIRSTCOORD311, FIRSTCOORD312, FIRSTCOORD313, FIRSTCOORD314, FIRSTCOORD315, *****
08355 FIRSTCOORD316, FIRSTCOORD317, FIRSTCOORD318, FIRSTCOORD319, FIRSTCOORD320, *****
08360 FIRSTCOORD321, FIRSTCOORD322, FIRSTCOORD323, FIRSTCOORD324, FIRSTCOORD325, *****
08365 FIRSTCOORD326, FIRSTCOORD327, FIRSTCOORD328, FIRSTCOORD329, FIRSTCOORD330, *****
08370 FIRSTCOORD331, FIRSTCOORD332, FIRSTCOORD333, FIRSTCOORD334, FIRSTCOORD335, *****
08375 FIRSTCOORD336, FIRSTCOORD337, FIRSTCOORD338, FIRSTCOORD339, FIRSTCOORD340, *****
08380 FIRSTCOORD341, FIRSTCOORD342, FIRSTCOORD343, FIRSTCOORD344, FIRSTCOORD345, *****
08385 FIRSTCOORD346, FIRSTCOORD347, FIRSTCOORD348, FIRSTCOORD349, FIRSTCOORD350, *****
08390 FIRSTCOORD351, FIRSTCOORD352, FIRSTCOORD353, FIRSTCOORD354, FIRSTCOORD355, *****
08395 FIRSTCOORD356, FIRSTCOORD357, FIRSTCOORD358, FIRSTCOORD359, FIRSTCOORD360, *****
08400 FIRSTCOORD361, FIRSTCOORD362, FIRSTCOORD363, FIRSTCOORD364, FIRSTCOORD365, *****

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08410  GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08420  GRIODCHAR(P1,P21,TYPEGROUND)=1
08430  end;
08440  procedure forground(p1,p21:integer);
08450  (*proceeds for ground when it has 2 or more characteristics at the same color *)
08460  begin
08470   value2:=1;
08480   begin
08490    GROUND:=GRIODCHAR(P1,P21,TYPEGROUND);
08500    GRIODCHAR(P1,P21,TYPEGROUND):=7;
08510    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08520    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08530    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08540    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08550    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08560    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08570    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08580    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08590    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08600    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08610    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08620    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08630    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08640    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08650    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08660    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08670    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08680    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08690    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08700    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08710    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08720    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08730    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08740    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08750    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08760    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08770    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08780    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08790    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08800    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08810    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08820    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08830    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08840    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08850    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08860    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08870    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08880    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08890    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08900    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08910    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08920    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08930    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08940    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08950    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;
08960    GRIODCHAR(P1,P21,GROUNDPTR)=PTR;

```

```

08970 end;
08980 end;
08990 procedure READCHAR;
09000 **READES A CHARACTER FROM THE FILE MAPDAT**
09010 var
09020 ALP:char;
09030 begin
09040 read(ALP);
09050 until ALP<>' ' do
09060 while not (EIO(ALP) or (ALP=' ')) do read(MAPDAT,ALP);
09070 end;
09080 **
09090 procedure CONVERTDIR(var DIRECTION:range);
09100 (** CONVERTS DIRS TO DIRECTION AND OUTPUTS IT IN DIRECTION **)
09110 **
09120 begin
09130 case DIRECTION of
09140 0: DIRECTION:=1;
09150 1: DIRECTION:=2;
09160 2: DIRECTION:=3;
09170 3: DIRECTION:=4;
09180 4: DIRECTION:=5;
09190 5: DIRECTION:=6;
09200 6: DIRECTION:=7;
09210 end;
09220 **
09230 procedure READINCH;
09240 (** READS DIRECTLY INPUT UPTO 12 CHARACTERS FROM FILE MAPDAT **)
09250 var
09260 INCH:char; I:integer;
09270 begin
09280 for I:=1 to 12 do
09290 INCH:=INCH;
09300 while INCH<>' ' do read(MAPDAT,INCH);
09310 while (not EIO(MAPDAT)) and (INCH<>' ') do
09320 INCH:=INCH; I:=I+1; read(MAPDAT,INCH);
09330 if I>12 then
09340 else
09350 if EIO(MAPDAT) then INCH:=INCH;
09360 end;
09370 **
09380 procedure READINCH3;
09390 **
09400 **
09410 begin
09420 read(INCH3);
09430 **
09440 **
09450 end;
09460 **
09470 procedure SPLIT(var SPIE:SPRITE);
09480 **
09490 begin
09500 SPIE:=SPIE;
09510 end;
09520 **

```



```

09530 procedure FILLUPSTACK;
09540 (* completes the trip heights after the contours have been described *)
09550 type
09560   TOP = integer;
09570   HT, AD: integer;
09580   only;
09590 var
09600   STACK: array(0..1000) of RECORD;
09610   TOP: integer;
09620   A: integer;
09630   procedure FILLUPSTACK(FROMNO, TONNO, HT: integer);
09640   (* fills the heights HT between pts FROMNO to TONNO *)
09650   only;
09660   var
09670   X: integer;
09680   Y: boolean;
09690   if TOP=0 then Y:=0;
09700   else
09710     begin
09720       for X:=FROMNO to TONNO do
09730         if GROUND(X, II).ALTITUDE=0 then
09740           GROUND(X, II).ALTITUDE:=HT;
09750       STACK(TOP).HT:=0; STACK(TOP).AD:=0; TOP:=TOP+1;
09760       add;
09770       add;
09780       procedure PUSH(HEIGHT: integer);
09790       (* stores the height HEIGHT in stack for matching *)
09800       only;
09810       var
09820       PUSHSTACK: boolean;
09830       begin
09840         PUSHSTACK:=false;
09850         if TOP<2 then PUSHSTACK:=true
09860         else
09870           begin
09880             if ((STACK(TOP).HT>STACK(TOP-1).HT)and(HEIGHT>STACK(TOP).HT))
09890             then PUSHSTACK:=true
09900             else
09910               if ((STACK(TOP).HT<STACK(TOP-1).HT)and(HEIGHT<STACK(TOP).HT))
09920               then PUSHSTACK:=
09930                 true
09940                 else
09950                   if HEIGHT=STACK(TOP-1).HT then
09960                     FILLUPSTACK(STACK(TOP-1).HT, NUMBER, HEIGHT); STACK(TOP).HT:=0;
09970                     STACK(TOP)
09980                     .AD:=0; TOP:=TOP+1;
09990                     end
10000                   else Y:=0;
10010                   add;
10020                   if PUSHSTACK then
10030                     begin
10040                       TOP:=TOP+1;
10050                       if TOP>10 then Y:=0;
10060                       else
10070                         begin

```

```

10090 with STACKLIST;
10100 begin
10110   HP:=HP+50;
10120   end;
10130   end;
10140   end;
10150   end;
10160   procedure INITSTACK;
10170   (* initializes the stack for starting *)
10180   a:
10190   *****
10200   var
10210   ts:integer;
10220   begin
10230   for ts:=0 to 13 do with STACKLIST do
10240   begin
10250     HP:=0;
10260     end;
10270   for ts:=0
10280     end;
10290   for ts:=1 to 40 do
10300     begin
10310     INITSTACK;
10320     for ts:=1 to 40 do
10330       begin
10340         if GRIDCHAR(J,I).ALTITUDE=0 then
10350           begin
10360             if STACKLIST(J).HP*GRIDCHAR(J,I).ALTITUDE then
10370               push(GRIDCHAR(J,I).ALTITUDE,I)
10380             else
10390               push(GRID(STACKLIST(J).HP,I),STACKLIST(J).HP)
10400             end;
10410           end;
10420         end;
10430       end;
10440     for ts:=1 to 7 do
10450       begin
10460         case I of
10470           1:FIXEDWORD:='RIVER';
10480           2:FIXEDWORD:='CAVAL';
10490           3:FIXEDWORD:='ROAD';
10500           4:FIXEDWORD:='CRDP/PRIG';
10510           5:FIXEDWORD:='MINE/PRIG';
10520           6:FIXEDWORD:='MARSH/';
10530           7:FIXEDWORD:='CLIFF';
10540         end;
10550         local
10560         READCHAR;ERROR:=false;
10570         exit if CH#';
10580         if I<3 then
10590           begin
10600             READ(MAPAT,LOTH);
10610             READ(MAPAT,DEPTH);
10620           end
10630         else
10640

```

```

10650  if i=7 then
10660      begin
10670          read(a2,a3,a4,a5,a6,a7,a8,a9);
10680      end;
10690      read(a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10700      write(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10710      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10720      exit if ((error=finish) or (not isnumber(error)));
10730      goto (nextpointer);
10740      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10750      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10760      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
10770      repeat
10780          currentpointer:=lastpointer;
10790          cur1:=currentpointer[1];cur2:=currentpointer[2];
10800          call nextid(cur1,cur2,direction);
10810          currentpointer[1]:=cur1;currentpointer[2]:=cur2;
10820          if ((currentpointer[1]<41) and ((currentpointer[1]>0)
10830              and (currentpointer[2]<41) and ((currentpointer[2]>0))) then
10840              begin
10850                  if i<7 then
10860                      begin
10870                          filladvgrid;fillpresentgrid;
10880                      end
10890                      else gridchar(lastpointer[1],lastpointer[2],altitude
10900                          :=height;
10910                          lastpointer:=currentpointer;firstpoint:=false;
10920                      end
10930                      else
10940                          begin
10950                              use(i);
10960                              error:=true;
10970                              end
10980                              until
10990                                  ((currentpointer=nextpointer) or (error));
11000                                  if (currentpointer=nextpointer then use(i);
11010      end;
11020      end;
11030      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
11040      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
11050      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a79,a80,a81,a82,a83,a84,a85,a86,a87,a88,a89,a90,a91,a92,a93,a94,a95,a96,a97,a98,a99,a100,a101,a102,a103,a104,a105,a106,a107,a108,a109,a110,a111,a112,a113,a114,a115,a116,a117,a118,a119,a120);
11060      read(a1,a2,a3,a4,a5,a6,a7,a8,a9,a10,a11,a12,a13,a14,a15,a16,a17,a18,a19,a20,a21,a22,a23,a24,a25,a26,a27,a28,a29,a30,a31,a32,a33,a34,a35,a36,a37,a38,a39,a40,a41,a42,a43,a44,a45,a46,a47,a48,a49,a50,a51,a52,a53,a54,a55,a56,a57,a58,a59,a60,a61,a62,a63,a64,a65,a66,a67,a68,a69,a70,a71,a72,a73,a74,a75,a76,a77,a78,a
```



```

11210 (** checks if the line of sight visibility is there or not **)
11220 var A,LOC1:=0;begin
11230 CHECK:=STARTX/ENDX,ENDY,CURRENTX,CURRENTY:=1;
11240 CURRANG:=0;CALCANG:=0;
11250 for I:=1 to 1000 do
11260 begin
11270 if (CURRENTX-CALCANG) < 0 then
11280 begin
11290 CURRENTX:=CURRENTX + INCR;
11300 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11310 end;
11320 if (CURRENTX-CALCANG) < 0 then
11330 begin
11340 CURRENTX:=CURRENTX + INCR;
11350 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11360 end;
11370 if (CURRENTX-CALCANG) < 0 then
11380 begin
11390 CURRENTX:=CURRENTX + INCR;
11400 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11410 end;
11420 if (CURRENTX-CALCANG) < 0 then
11430 begin
11440 CURRENTX:=CURRENTX + INCR;
11450 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11460 end;
11470 if (CURRENTX-CALCANG) < 0 then
11480 begin
11490 CURRENTX:=CURRENTX + INCR;
11500 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11510 end;
11520 if (CURRENTX-CALCANG) < 0 then
11530 begin
11540 CURRENTX:=CURRENTX + INCR;
11550 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11560 end;
11570 if (CURRENTX-CALCANG) < 0 then
11580 begin
11590 CURRENTX:=CURRENTX + INCR;
11600 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11610 end;
11620 if (CURRENTX-CALCANG) < 0 then
11630 begin
11640 CURRENTX:=CURRENTX + INCR;
11650 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11660 end;
11670 if (CURRENTX-CALCANG) < 0 then
11680 begin
11690 CURRENTX:=CURRENTX + INCR;
11700 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11710 end;
11720 if (CURRENTX-CALCANG) < 0 then
11730 begin
11740 CURRENTX:=CURRENTX + INCR;
11750 CURRENTY:=TRUNC((CURRENTX-C)/4)+0.5)
11760 end;

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```

begin
  readword;
  if word = ' ' then
    begin
      ap:=false;h:=false;s:=false;
      repeat
        if word='ap'
          begin ap:=true;readword
        end;
        if word='se'
          begin s:=true;readword
        end;
        if word='swake'
          begin sw:=true;readword
        end;
        if word='all'
          begin all:=true;readword
        end
      until (word='ap'
        and all=true;
        writeLn('K:',10,JK:6,'OF TROP:',10,JK:6,'REPORTING AMMUNITION BALANCE:',32,
          WRITELN(TTY,'TYPE:',20,QUANTITY:20);
        if ((sw=true)or(all=true)) then WRITELN(TTY,'AP:',10,TWKDATEIK,JK1,AMNCAP,IV01:2;
        then
          WRITELN(TTY,'SWAKE:',20,TWKDATEIK,JK1,AMNCAP,IV02:19);
          if ((h=true)or(all=true)) then WRITELN(TTY,'HE:',20,TWKDATEIK,JK1,AMNCAP,IV03:19)
        end;
        procedure TASKSTATUS(TA:boolean);(*REPORTS STATUS OF OWN TANK OR OTHER TANK*)
          (* depending on the type of command reports the status of self or of other tanks
            like RUGGED, MOVING, etc *)
        ***
        var
          J,K:integer;TEMP:packed array[1..4]of char;LOCREC:boolean;
        begin
          LOCREC:=false;
          if TA=true then
            if word='LOC'
              begin
                readword; for k:=1 to 4 do TEMP[k]:=word[k];
                LOCREC:=true
              end
            else
              begin
                TEMP[2]:=NUMWORD[2];J:=NUMWORD[1];readword;
                number:=LOC
              end
            if word='LOC'
              begin
                readword;for k:=1 to 6 do TEMP[k]:=word[k];
                LOCREC:=true
              end
            end
          else
            begin
                TEMP[2]:=NUMWORD[2];J:=NUMWORD[1];readword;
                number:=LOC
            end
            if word='LOC'
              begin
                readword;for k:=1 to 6 do TEMP[k]:=word[k];
                LOCREC:=true
              end
            end
          end
          WRITELN(TTY,'TANK:',10,JK:3,'OF TROP:',10,JK:3);
          if TA=true then

```

```

13450 begin TK:=1; TK:=31;
13460 WRITE(CITY, REPORTING STATUS OF TANK:30, T:3, OF TANKID:10, T:30);
13470 IF LOCATED=TRUE LOGO PRICELN(CITY, located at grid ref , T:30);
13480 end;
13490 else
13500 WRITE(CITY, REPORTING STATUS OF SELF:30);
13510 IF LOCATED=TRUE LOGO PRICELN(CITY, located at grid ref , T:30);
13520 end;
13530 if LOCATED=TRUE then MSG(4);
13540 if LOCATED=FALSE then MSG(5);
13550 else if LOCATED=TRUE then MSG(6);
13560 if LOCATED=FALSE then MSG(7);
13570 if LOCATED=TRUE then MSG(8);
13580 if LOCATED=FALSE then MSG(9);
13590 if LOCATED=TRUE then MSG(10);
13600 if LOCATED=FALSE then MSG(11);
13610 if LOCATED=TRUE then MSG(12);
13620 if LOCATED=FALSE then MSG(13);
13630 if LOCATED=TRUE then MSG(14);
13640 if LOCATED=FALSE then MSG(15);
13650 if LOCATED=TRUE then MSG(16);
13660 if LOCATED=FALSE then MSG(17);
13670 if LOCATED=TRUE then MSG(18);
13680 if LOCATED=FALSE then MSG(19);
13690 if LOCATED=TRUE then MSG(20);
13700 if LOCATED=FALSE then MSG(21);
13710 if LOCATED=TRUE then MSG(22);
13720 if LOCATED=FALSE then MSG(23);
13730 if LOCATED=TRUE then MSG(24);
13740 if LOCATED=FALSE then MSG(25);
13750 if LOCATED=TRUE then MSG(26);
13760 if LOCATED=FALSE then MSG(27);
13770 if LOCATED=TRUE then MSG(28);
13780 if LOCATED=FALSE then MSG(29);
13790 if LOCATED=TRUE then MSG(30);
13800 if LOCATED=FALSE then MSG(31);
13810 if LOCATED=TRUE then MSG(32);
13820 if LOCATED=FALSE then MSG(33);
13830 if LOCATED=TRUE then MSG(34);
13840 if LOCATED=FALSE then MSG(35);
13850 if LOCATED=TRUE then MSG(36);
13860 if LOCATED=FALSE then MSG(37);
13870 if LOCATED=TRUE then MSG(38);
13880 if LOCATED=FALSE then MSG(39);
13890 if LOCATED=TRUE then MSG(40);
13900 if LOCATED=FALSE then MSG(41);
13910 if LOCATED=TRUE then MSG(42);
13920 if LOCATED=FALSE then MSG(43);
13930 if LOCATED=TRUE then MSG(44);
13940 if LOCATED=FALSE then MSG(45);
13950 if LOCATED=TRUE then MSG(46);
13960 if LOCATED=FALSE then MSG(47);
13970 if LOCATED=TRUE then MSG(48);
13980 if LOCATED=FALSE then MSG(49);
13990 if LOCATED=TRUE then MSG(50);
14000 if LOCATED=FALSE then MSG(51);

```

```

140100 else error(3)
140200 end
140300
140400 procedure calc_posn(a,b:integer);
140500 (* calculates the position for the tank *)
140600 (* a,b are the coordinates of the tank *)
140700 (* c is the distance to the target *)
140800 (* d is the direction to the target *)
140900 (* e is the distance to the target *)
141000 (* f is the direction to the target *)
141100 (* g is the distance to the target *)
141200 (* h is the direction to the target *)
141300 (* i is the distance to the target *)
141400 (* j is the direction to the target *)
141500 (* k is the distance to the target *)
141600 (* l is the direction to the target *)
141700 (* m is the distance to the target *)
141800 (* n is the direction to the target *)
141900 (* o is the distance to the target *)
142000 (* p is the direction to the target *)
142100 (* q is the distance to the target *)
142200 (* r is the direction to the target *)
142300 (* s is the distance to the target *)
142400 (* t is the direction to the target *)
142500 (* u is the distance to the target *)
142600 (* v is the direction to the target *)
142700 (* w is the distance to the target *)
142800 (* x is the direction to the target *)
142900 (* y is the distance to the target *)
143000 (* z is the direction to the target *)
143100 (* aa is the distance to the target *)
143200 (* ab is the direction to the target *)
143300 (* ac is the distance to the target *)
143400 (* ad is the direction to the target *)
143500 (* ae is the distance to the target *)
143600 (* af is the direction to the target *)
143700 (* ag is the distance to the target *)
143800 (* ah is the direction to the target *)
143900 (* ai is the distance to the target *)
144000 (* aj is the direction to the target *)
144100 (* ak is the distance to the target *)
144200 (* al is the direction to the target *)
144300 (* am is the distance to the target *)
144400 (* an is the direction to the target *)
144500 (* ao is the distance to the target *)
144600 (* ap is the direction to the target *)
144700 (* aq is the distance to the target *)
144800 (* ar is the direction to the target *)
144900 (* as is the distance to the target *)
145000 (* at is the direction to the target *)
145100 (* au is the distance to the target *)
145200 (* av is the direction to the target *)
145300 (* aw is the distance to the target *)
145400 (* ax is the direction to the target *)
145500 (* ay is the distance to the target *)
145600 (* az is the direction to the target *)
145700 (* ba is the distance to the target *)
145800 (* bb is the direction to the target *)
145900 (* bc is the distance to the target *)
146000 (* bd is the direction to the target *)
146100 (* be is the distance to the target *)
146200 (* bf is the direction to the target *)
146300 (* bg is the distance to the target *)
146400 (* bh is the direction to the target *)
146500 (* bi is the distance to the target *)
146600 (* bj is the direction to the target *)
146700 (* bk is the distance to the target *)
146800 (* bl is the direction to the target *)
146900 (* bm is the distance to the target *)
147000 (* bn is the direction to the target *)
147100 (* bo is the distance to the target *)
147200 (* bp is the direction to the target *)
147300 (* bq is the distance to the target *)
147400 (* br is the direction to the target *)
147500 (* bs is the distance to the target *)
147600 (* bt is the direction to the target *)
147700 (* bu is the distance to the target *)
147800 (* bv is the direction to the target *)
147900 (* bw is the distance to the target *)
148000 (* bx is the direction to the target *)
148100 (* by is the distance to the target *)
148200 (* bz is the direction to the target *)
148300 (* ca is the distance to the target *)
148400 (* cb is the direction to the target *)
148500 (* cc is the distance to the target *)
148600 (* cd is the direction to the target *)
148700 (* ce is the distance to the target *)
148800 (* cf is the direction to the target *)
148900 (* cg is the distance to the target *)
149000 (* ch is the direction to the target *)
149100 (* ci is the distance to the target *)
149200 (* cj is the direction to the target *)
149300 (* ck is the distance to the target *)
149400 (* cl is the direction to the target *)
149500 (* cm is the distance to the target *)
149600 (* cn is the direction to the target *)
149700 (* co is the distance to the target *)
149800 (* cp is the direction to the target *)
149900 (* cq is the distance to the target *)
150000 (* cr is the direction to the target *)

```

```

begin
    LP:=LP+UP^2;
    while (LP<(ISLANDMARK*(LP#nil)) do
        begin
            if ANDOP>0 then LP:=LP*.RUINX
            else LP:=LP*.GUESS
        end
    until LP=0 or LP=ISLANDMARK
end;

procedure checkref(var A,B:integer);
(* checks two points, firstly if the word is a number or LANDMARK, if it is
   then converts and puts its gridref in A,B *)
var C:integer;
begin
    if LP=ISLANDMARK then CHECKLANDMARK(G);
    if ISLANDMARK OF ISLANDMARK then
        begin
            C:=C+1;
            if ISLANDMARK THEN CONVERT(INIVAL,A,B)
            else CONVERT(G,A,B)
        end
    end;
    procedure MOVE: (* ENTERS THE ROUTE TO BE TAKEN BY THE PAIR ON THE MOVE *)
    (* This is part of table filling. If fills the route to be taken
       by the point specified in input constant. *)
    (* max points left to go, the no of points are kept in M, subjective *)
    is stored in CURSOR SUBJECTIVE *)
    var J,I,C:integer;A,B:integer;
    begin
        I:=0;for J:=1 to 10 do
            begin
                MO^.ROUTE[J].X:=0;
                MO^.ROUTE[J].Y:=0
            end
        until MO^.ROUTE[10].X:=M;MO^.ROUTE[10].Y:=0
        READWORD;
        exit if (MOPO=>);
        checkref(A,B);
        if (CISNUMBER OR ISLANDMARK) then
            I:=I+1;MO^.ROUTE[I].X:=M;MO^.ROUTE[I].Y:=0
        else ERROR(18)
        end
    end
end;
```


[illegible]


```

16250 READJOBID;
16260 IF (ISJOBID OF 150) THEN MARK THEN
16270 MARK;
16280 IF (MARK) THEN START:=true;
16290 IF (START:=true) THEN
16300 IF (START:=true) THEN
16310 IF (START:=true) THEN
16320 IF (START:=true) THEN
16330 IF (START:=true) THEN
16340 IF (START:=true) THEN
16350 IF (START:=true) THEN
16360 IF (START:=true) THEN
16370 IF (START:=true) THEN
16380 IF (START:=true) THEN
16390 IF (START:=true) THEN
16400 IF (START:=true) THEN
16410 IF (START:=true) THEN
16420 IF (START:=true) THEN
16430 IF (START:=true) THEN
16440 IF (START:=true) THEN
16450 IF (START:=true) THEN
16460 IF (START:=true) THEN
16470 IF (START:=true) THEN
16480 IF (START:=true) THEN
16490 IF (START:=true) THEN
16500 IF (START:=true) THEN
16510 IF (START:=true) THEN
16520 IF (START:=true) THEN
16530 IF (START:=true) THEN
16540 IF (START:=true) THEN
16550 IF (START:=true) THEN
16560 IF (START:=true) THEN
16570 IF (START:=true) THEN
16580 IF (START:=true) THEN
16590 IF (START:=true) THEN
16600 IF (START:=true) THEN
16610 IF (START:=true) THEN
16620 IF (START:=true) THEN
16630 IF (START:=true) THEN
16640 IF (START:=true) THEN
16650 IF (START:=true) THEN
16660 IF (START:=true) THEN
16670 IF (START:=true) THEN
16680 IF (START:=true) THEN
16690 IF (START:=true) THEN
16700 IF (START:=true) THEN
16710 IF (START:=true) THEN
16720 IF (START:=true) THEN
16730 IF (START:=true) THEN
16740 IF (START:=true) THEN
16750 IF (START:=true) THEN
16760 IF (START:=true) THEN
16770 IF (START:=true) THEN
16780 IF (START:=true) THEN
16790 IF (START:=true) THEN
16800 IF (START:=true) THEN

```

```

16810 begin
16820 CHECKMOVTAB:=REMOVED;
16830 if ISMOVABLE then
16840 begin
16850 if MOV=0 then
16860 begin
16870 state:=state(1);
16880 state:=true;
16890 end
16900 else OVERMOVED;
16910 end
16920 else
16930 begin
16940 MOV:=0; ULINK:=nil; NOC.TANKNO:=TANKNUMBER; NOC.OBJECTIVE:=0;
16950 if MOV=10 then ENTERMOVPOD;
16960 else OVERDISLOVED;
16970 end
16980 end;
16990 *****
17000 procedure PRINTMOVTAB;(*PRINTS THE MOVE TABLE*)
17010 *****
17020 begin
17030 MOV:=0; TANK NO:=12; DESTINATION:=20; STATE:=15; OBJECTIVE:=13);
17040 while MOVABASE < 30
17050 begin
17060 MOV:=MOV; ULINK;
17070 PRINT MOV, TANKNO:12, MR.DEST.X:10, MR.DEST.Y, MR.STATE:12,
17080 OBJECTIVE:13);
17090 end
17100 *****
17110 end;
17120 *****
17130 procedure ADULETEFAB(FTEMP:FPTR);(*deletes a record with ptr *)
17140 *****
17150 begin
17160 if FTEMP=GLASS then
17170 begin
17180 FLAST:=FTEMP; ULINK;
17190 FTEMP; ULINK; ULINK:=nil;
17200 end
17210 else
17220 begin
17230 ULINK; ULINK:=FTEMP; ULINK;
17240 FTEMP; ULINK; ULINK:=FTEMP; ULINK;
17250 end;
17260 *****
17270 function FIRETABPR(I,J:integer):FPTR;
17280 (* checks if the tank I, J is already fired , if it is then
17290 returns its ptr value fptr *)
17300 *****
17310 var
17320 FTEMP:FPTR;
17330 begin FTEMP:=FROD; FIRETABOPR:=nil;
17340 while FTEMP<GLAST do
17350 begin FTEMP:=FTEMP; ULINK;
17360 if (FTEMP.SOURCEPR[I]=I) and (FTEMP.SOURCEPR[J]=J) then

```

[illegible]

[illegible]

```

19900 FP^.Y(PJFIRETAB)
19910 end
19920 else
19930   begin ERROR(2);
19940   goto 15
19950 end;
19960 if ((WORD='SHELV') or (WORD='SHEUGS')) then
19970   begin
19980     READ(FP^.X);
19990     if (WORD='LV') then
20000       begin
20010         if ((WORD='LV') or (WORD='TANK')) then
20020           begin
20030             READ(FP^.NUMBER);
20040             FP^.DESTTK[1]:=NUMWORD[1];
20050             FP^.DESTTK[2]:=NUMWORD[2];
20060             if (NUMBER=0) then
20070               begin
20080                 if (WORD='LV') then
20090                   begin
20100                     if (not CHECKOTHERdirection) and (WORD='LV') then
20110                       MSG(17);
20120                     FP^.DESTLOC.X:=TNKDAT[FP^.DESTTK[1],FP^.
20130                     DESTTK[2]];
20140                     MAPCORD.X:=
20150                     FP^.DESTLOC.Y:=TNKDAT[FP^.DESTTK[1],FP^.
20160                     DESTTK[2]];
20170                     MAPCORD.Y:=
20180                     JOIN:=true;
20190                     end;
20200                     end
20210                   else
20220                     begin
20230                       ERROR(24);
20240                       goto 15
20250                     end
20260                   else
20270                     ERROR(25)
20280                   end
20290                 else
20300                   if (WORD='LV') then
20310                     begin
20320                       if (WORD='LV') then
20330                         begin
20340                           ERROR(27)
20350                         end
20360                       else MSG(18)
20370                     end
20380                   if JOIN=true then JOINFIRETAB;
20390                   end;
20400                   if (not (PROCESSM3Vtank(PTR:MPTR);
20410                   (* processes the move of the tank, checking for the obstacles and taking action

```


[illegible]

```

19610 var
19620 sub:packed array(1..255) of byte;
19630 dir:array(1..255) of byte;
19640 if dir[0] = 0 then
19650   begin
19660     sub:=0;
19670     dir:=0;
19680     dir:=0;
19690     dir:=0;
19700     dir:=0;
19710     dir:=0;
19720     dir:=0;
19730     dir:=0;
19740     dir:=0;
19750     dir:=0;
19760     dir:=0;
19770     dir:=0;
19780     dir:=0;
19790     dir:=0;
19800     dir:=0;
19810     dir:=0;
19820     dir:=0;
19830     dir:=0;
19840     dir:=0;
19850     dir:=0;
19860     dir:=0;
19870     dir:=0;
19880     dir:=0;
19890     dir:=0;
19900     dir:=0;
19910     dir:=0;
19920     dir:=0;
19930     dir:=0;
19940     dir:=0;
19950     dir:=0;
19960     dir:=0;
19970     dir:=0;
19980     dir:=0;
19990     dir:=0;
20000     dir:=0;
20010     dir:=0;
20020     dir:=0;
20030     dir:=0;
20040     dir:=0;
20050     dir:=0;
20060     dir:=0;
20070     dir:=0;
20080     dir:=0;
20090     dir:=0;
20100     dir:=0;
20110     dir:=0;
20120     dir:=0;
20130     dir:=0;
20140     dir:=0;
20150     dir:=0;
20160     dir:=0;

```

[illegible]

[illegible]

21290 SROUNDFACTOR(CRITCHALVL2,Y21,TYPEGR0000);
21300 SROUNDFACTOR;
21310 end;
21320 if (not FINISH)or(CROSSED))then
21330 begin
21340 PTR^.LOC.X:=X2;PTR^.LOC.Y:=Y2;
21350 SPEED:=TRUNC(SPEED*FACTOR);
21360 INKDAI1IK,JKI,ABCD0,X:=X2;INKDAI1IK,JKI,ABCD0,Y:=Y2;
21370 CURRENTTIME:=TRUNC((36*DISTANCE)/(SPEED*10));
21380 UPDATETUE:INKDAI1IK,JKI,DRIFTAS:=DRIFT0+1;
21390 end;
21400 end;
21410 begin
21420 TIMECOUNT:=0;FINISH:=false;FIRSTTIME:=true;
21430 CHANGEDIRECTION;
21440 SKIP(3);CROSSED:=false;
21450 IK:=(PTR^.JAWA/10)div10;JK:=(PTR^.JAWA/10)mod10;
21460 CURRRETIME:=0;
21470 repeat
21480 GETDIRECTION(PTR^.LOC.X,INEX,X,PTR^.LOC.Y,INEX,Y,DIRECTION);
21490 COMPUSTIME;
21500 TIMECOUNT:=TIMECOUNT+CURRRETIME;
21510 if (PTR^.LOC.X=PTR^.DEST.X)and(PTR^.LOC.Y=PTR^.DEST.Y)then
21520 begin
21530 FINISH:=true;REACHEDestination:=true;INKDAI1IK,JKI,ABCD0:=false;
21540 end;
21550 if not FINISH then
21560 if (INEXIX=PTR^.LOC.X)and(INEXIX=PTR^.LOC.Y) then
21570 begin
21580 PTR^.CORROBJECTIVE:=PTR^.CORROBJECTIVE+1;
21590 CHANGEDIRECTION
21600 end
21610 until ((TIMESTEP<(TIMECOUNT+0.5*CURRRETIME))or(FIRSTTIMEor(incarnation)));
21620 end;
21630 procedure MOVETASKS;
21640 (*moves the tasks from a location to another when command has been given *)
21650 var
21660 TEMP,PTR:MPTR;
21670 begin
21680 PTR:=MOVETABROOT.UNITK;
21690 while PTR#nil do
21700 begin
21710 REACHEDestination:=false;
21720 if PTR^.STATE then PROCESS*overtask(PTR);
21730 TEMP:=PTR;PTR:=PTR^.UNITK;
21740 if REACHEDestination then DELETEMOVETABO(TEMP);
21750 end
21760 end;
21770 end;
21780 procedure FIRE;
21790 (*FIRE the shell that has been commanded for the task to fire *)
21800 var
21810

[illegible]

```

00000000 SKIP(20) FIRE REPORT(I), J, I:=I+J;
00000000 IF ((C=77, MARK=1, I=1, J=1, DIST=999, TIME=999, LOC=
00000000 999, JUK=999, X=2, PR=5)) THEN GOTO 7;
00000000 END;
00000000 *** *****
00000000 procedure JUKreportfire;
00000000 (* initializes the report for tanks so that in the same course
00000000 the fire is not reported over the same tank more than once *)
00000000 *****
00000000 var I,J:integer;
00000000 begin
00000000   for I:=1 to 5 do
00000000     for J:=1 to 3 do
00000000       begin
00000000         fireReport(I,J):=false;
00000000       end;
00000000   LUCHI:=false;
00000000 end;
00000000 *****
00000000 procedure reportHit(I,J:integer);
00000000 (* in case the tank target has been hit this reported in this procedure *)
00000000 *****
00000000 begin
00000000   if not Hit(I,J) then
00000000     begin
00000000       FUKDAFI,I,STATUS,VIRTRAFISID:=true;
00000000       WRITE(CRT,'MARK',PR,SUBREPORT(I),FUC,SUBREPORT(I));
00000000       REPORT(S,VIRTRAFISID,ENG,X,FUC,MARK:=121);
00000000       BREAK;Hit(I,J):=true;
00000000     end;
00000000   end;
00000000   begin
00000000     if ((I#JK)and(J#JK)) then
00000000       reportFire(I,J,angivPE);
00000000     if ((angivPE#1)or(chitype#1)) then
00000000       begin
00000000         if distance < 1000 then distype:=0
00000000           else
00000000             if distance < 2000 then distype:=1
00000000               else
00000000                 if distance < 4000 then distype:=2
00000000                   else distype:=3;
00000000                 angle:=abs(FKDKOATIK,JKI,PRATAFN-VIKKOATIK,JKI,PRATAFN);
00000000                 if (angle < 45) or (angle > 315) then angivPE:=1
00000000                   else
00000000                     if (angle>135) and (angle<225) then angivPE:=1
00000000                       else angivPE:=2;
00000000                     if required then
00000000                       reportHit(I,J)
00000000                     else

```

```

22970 begin
22980 case 0151299 of
22990 0:
23000
23010
23020
23030
23040
23050
23060
23070
23080
23090
23100
23110
23120
23130
23140
23150
23160
23170
23180
23190
23200
23210
23220
23230
23240
23250
23260
23270
23280
23290
23300
23310
23320
23330
23340
23350
23360
23370
23380
23390
23400
23410
23420
23430
23440
23450
23460
23470
23480
23490
23500
23510
23520
begin
case 0151299 of
1: with PKDAT(I, J), STATUS to
begin
CAVMDV:=false;
SHOCKED:=true;
if:
2: PKDAT(I, J), STATUS, CAVMDV:=
false;
3: REPRORH(I, J)
end
else
else PKDAT(I, J), STATUS, SHOCKED:=true;
1:
if AVTYPE=2 then
begin
case AVTYPE of
1: with PKDAT(I, J), STATUS to
begin
CAVMDV:=false;
SHOCKED:=true;
if:
2: PKDAT(I, J), STATUS, CAVMDV:=
false;
3: REPRORH(I, J)
end
else
else AVTYPE=2 then PKDAT(I, J), STATUS,
CAVMDV:=false
else
begin
PKDAT(I, J), STATUS, SHOCKED:=true;
end;
2:
if AVTYPE=3 then PKDAT(I, J), STATUS,
CAVMDV:=false
else
PKDAT(I, J), STATUS, SHOCKED:=true;
others:
end;
end;
end;
end;
begin
for I:=1 to 5 do
for JJ:=1 to 5 do
begin
if (PKDAT(I, JJ), MAPCOR, X=017X) and
(PKDAT(I, JJ), MAPCOR, X=017X) then

```

```

ANALYSEINIT(I,J,I,P,FR,TYPDEFVAL)
else
if ((ASSTPRKALL(J),J).APCDD.V-HIT)=0 then
CARSCORR(I,J).CORCOR(X-HIT)=0) then
ANALYSESHIP(I,J,I,P,FR,TYPDEFVAL);
end;
if ASSTPRKALL=0 then
if (CHIX=FR.DESTLOC.X)and((HUY=FR.DESTLOC.Y)or(DELIV) then
begin
WRITE(TTY,"TASK",FR.SOURCEID(1),FR.SOURCEID(2),I,
REPORTS,GIVING EFFECTIVE FIRE IN I,,J,X:Z,HUY:Z);
LOCHIT:=true;
end;
end;
**** INITIALISES THE REPORT ****
(* initialises the report *)
var
I,J:integer;
begin
for I:=1 to 5 do
for J:=1 to 3 do FIREPORT(I,J):=false;
end;
**** CALCULATE ROUNDS(FTEMP,FPR,var ROUNDS:integer) ****
(* calculates the rounds that are to be fired in that firestep *)
****
begin
if FTEMP.TIME < MINFSTEP then
begin
ROUNDS:=(MINFSTEP-FTEMP.TIME)*FTEMP.RATE;
FTEMP.TIME:=0;
if ROUNDS > FTEMP.TOTAL then ROUNDS:=FTEMP.TOTAL;
else
begin
FTEMP.TIME:=FTEMP.TIME - MINFSTEP;
ROUNDS:=0;
end;
end;
begin
FR:=PROT;REWRITE(FIREOUT);
while FR.BUTTKALL do
begin
FR:=FR;LINK:CALCULATEROUNDS(FR,0);IF PRORCFIRE(I,J):=false;
begin
PUS:=1;TVKDATER,SOURCE(K),FR.SOURCEID(1),STATUS,FR:=true;
CALCULATEDIST(CR,X,FR.SOURCELOC,Y,FR.DESTLOC,X,FR.DESTLOC,
Y,DISTANCE);
ASINE:=(CR.DESTLOC.Y - FR.SOURCELOC.Y)/DISTANCE;
ACOS:=(CR.DESTLOC.X - FR.SOURCELOC.X)/DISTANCE;
for J:=1 to 40 do
begin
if PUS#1 then PROR:=2- FR.HITPROR

```


[illegible]


```

begin
  FOR J:=1 TO NCH; I:=1+J; READ (AP, X(I));
  end;
  if I>12 then use 150(3)
  else
    if EQVAL(14APPA1) then 10XOLV:=1700
    while not EQVAL(14APPA1) do READ (AP, X(I));
    end;
  ***
  procedure DRAW;
  (* draws the details of the tap as listed in Table 3 *)
  ***
  var
    LASTX, LASTY: integer;
  ***
  procedure FILLGETTER(X, LASTX, Y, LASTY: integer);
  (* used for get pointer for the display, 0000053A P *)
  ***
  var
    PX, PY: real;
    TEMP: integer;
  begin
    PX:=real(TEMP);
    TEMP:=LASTX-X; PX:=X; PY:=Y;
    if TEMP=1 then PX:=X+0.5
    else
      if TEMP=(-1) then PX:=LASTX+0.5;
      TEMP:=LASTY-Y;
      if TEMP=1 then PY:=Y+0.5
      else
        TEMP:=(-1) then PY:=LASTY+1.5;
        if ((X#LASTX) or (Y#LASTY)) then
          begin
            LINE(PX/40, PY/40, 1); MARKER(X(I), Y(I));
          end;
        end;
      end;
    loop
      READ INPUT;
      NUMBER;
      exit if not ISNUMBER;
      CONVERT(IT(INIVAL, X1, Y1));
      LASTX:=X; LASTY:=Y;
      repeat
        READ (AP, X, Y);
        FILLGETTER(X, LASTX, Y, LASTY);
        LINE(RESOURCE(X), RESOURCE(Y), 1);
        MARKER(14ARK);
        LASTX:=X; LASTY:=Y;
      until ((X=X1) and (Y=Y1));
    end;
  ***
  procedure READCHAR; (* READS A CHARACTER FROM THE TITLE AREA *)
  ***
  var
    AP: char;
  begin

```

```

25770 repeat READ(MAPDAT,CH)
25780 until CH# (END(MAPDAT)or(ALP='')) to END(MAPDAT,END);
25790 while not (END(MAPDAT)or(ALP='')) to END(MAPDAT,END);
25800 end;
25810 begin
25820 RESET(MAPDAT);RESET(MAPD);
25830 REINITIALIZE;GIVE RETURN;
25840 RESET(FIRST);CURSOR(1);
25850 GIVE(0,0,0,0,0);
25860 D1:=0;D1:=0,0,0,0,0;
25870 D1:=0;D1:=0,0,0,0,0;
25880 D1:=0;D1:=0,0,0,0,0;
25890 D1:=0;D1:=0,0,0,0,0;
25900 YX:=0,0;
25910 CSIZEPH(120);CSIZE(60);
25920 for I:=1 to 7 do
25930 begin
25940 XX:=0,0;
25950 YY:=YI+0,125;
25960 for J:=1 to 7 do
25970 begin
25980 XX:=XX+0,125;
25990 LINE(XX,YY,0);
26000 MARKER(3);
26010 end;
26020 end;
26030 for I:=1 to 7 do
26040 begin
26050 loop
26060 READCHAR;
26070 exit if CH# 'Y';
26080 if I<3 then
26090 begin
26100 READLN(MAPDAT,0);READLN(MAPDAT,0);
26110 end
26120 else
26130 if I=7 then READLN(MAPDAT,0);
26140 READLN(MAPDAT,0);
26150 CONVERT(S2,X,Y);
26160 LINE(REDUCE(X),REDUCE(Y),0);
26170 FIRST:=true;
26180 if ((I=1)or(I=3)) then
26190 begin
26200 loop
26210 READ INPUT;NUMBER;
26220 exit if not (NUMBER;CONVERT(INTERVAL,X1,Y1);
26230 LINE(REDUCE(X1),REDUCE(Y1),0);X1:=X1+0,0,0,0,0;
26240 if I=1 then
26250 begin
26260 if X=X1 then X1:=0,0,0,0,0;
26270 else Y1:=0,0,0,0,0;
26280 if FIRST then
26290 begin FIRST:=false;LASTX:=REDUCE(X)+MINER;LASTY:=
26300 REDUCE(Y)+Y1+0;
26310 end;
26320 LINE(LASTX,LASTY,0);

```

```

330 BASICX:=REDUCE(XI)+VINCX:(ASTV:=REDUCE(YI)+VINCX;
26340 LINECLASTX:=ASTV,1);
26350 LINE(REDUCE(YI),REDUCE(XI),0);
26370 end;
26380 X:=XI;Y:=YI;
26390 end;
26400 else
26410 begin
26420 case I of
26430 1:3:MARK:=3;
26440 2:MARK:=1;
26450 4:MARK:=4;
26460 5:MARK:=5;
26470 6:MARK:=6;
26480 others:MARK:=10;
26490 end;
26500 MARKER(MARK);
26510 DRAW;
26520 end;
26530 end;
26540 DRAWLANDMARK(LWORD);DRAWMARK;
26550 DRAWPREP;
26560 WRITECN(TTY,'GIVE <RESP> TO CLEAR & CONTINUE');DRAWX;
26570 CURDEV(1);
26580 end;
26590 *****
26600 procedure COMMANDS:(PROCESSES THE TYPE OF COMMAND) *****
26610 begin READWORD;
26620 if WORD='READ' then REPORTPROC
26630 else WORD='MOVE'
26640 else WORD='FIRE'
26650 else WORD='SHOOT'
26660 else
26670 WRITECN(TTY,'YOUR STATEMENT',20,WORD:15,'END OF STATEMENT');
26680 BREAK
26690 end
26700 *****
26710 procedure NAME:(CERTAIN THE NAME OF TANK ADDRESS) *****
26720 (* the no of the tank is stored in IK-TANKNO,JK-TANKNO. *)
26730 (* if it then checks if the tank is neutralised. *)
26740 (* if it is neutralised then it is not allowed to be accessed *****
26750 *****
26760 *****
26770 *****
26780 *****
26790 *****
26800 *****
26810 *****
26820 *****
26830 *****
26840 *****
26850 *****
26860 *****
26870 *****
26880 *****
26890 *****

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26910 when COMMAND=;
26911     end
26912 else WRITELN(ITY, 'TANK ID ', JK:1, ' WRONG GIVE AGAIN');
26913 end;
26914 *****
26915 procedure CHECK;
26916 (* analyses the type of check required and takes action accordingly *)
26917 *****
26918 begin WRITELN(ITY, 'THE FOLLOWING CHECKS ARE POSSIBLE');
26919 WRITELN(ITY, '15, LISTING LANDMARKS ARE POSSIBLE');
26920 WRITELN(ITY, '15, LISTING CURRENTLY MOVING TANKS');
26921 WRITELN(ITY, '15, DRAWING TO DRAW THE MAP');
26922 WRITELN(ITY, '15, SETTING THE SET MAP DRAWING');
26923 WRITELN(ITY, '15, RETURNING THE SET MAP DRAWING');
26924 BREAK;
26925 case CH of
26926     'L': PRIMTAB(LMRODT); T:PRINTMOVTAB;
26927     'M': DRAWMAP; S:MAPREQUIRED:=true; D:MAPREQUIRED:=false;
26928     others:
26929         begin WRITELN(ITY, 'OUR ', CH, ' NOT RECOGNISED PLEASE REENTER');
26930         end;
26931 end;
26932 *****
26933 begin
26934     INITIALISE;
26935     INITGRID;
26936     INITTANK;
26937     FILLOTOP;
26938     FILTERL;
26939     READTIMES;
26940     1000;
26941     SKIP();
26942     if not FREEZE then
26943         begin ADVETANKS; MOVESHOCK; FIRE;
26944         end;
26945     if MAPREQUIRED then DRAWMAP;
26946     WRITE(ITY, 'YOUR COMMAND: '); BREAK;
26947     UPDATETIME;
26948     READLINE; READWORD; TESTNUMBER:=false;
26949     exit if WORD='END'
26950         if WORD='JK'
26951             then
26952                 TANKNAME
26953             else
26954                 if (WORD='HELPCOMND' or (WORD='HELP
26955                     ' then HELPCOMND
26956                 else
26957                     if WORD='LANDMARK'
26958                         then FILTERL
26959                     else
26960                         if WORD='CHECK'
26961                             then CHECK
26962                         else
26963                             if WORD='FREEZE'
26964                                 then FREEZE:=true
26965                             else
26966                                 if (WORD='CONTINUE'
26967                                     or (WORD='QUIT
26968                                         ')) then FREEZE:=
26969                                     false
26970                                 else ERROR(1)
26971                             end;
26972             end;
26973 end;

```